



A RATIONAL HARMONIC BALANCE APPROXIMATION FOR THE
DUFFING EQUATION OF MIXED PARITY

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Interesting analysis has been reported by Mickens and Semwogerere [1] recently recommending a rational function,

$$x(t) = A \cos \omega t / (1 + B \cos 2\omega t), \quad (1)$$

for the non-linear one-dimensional oscillator differential equation,

$$\ddot{x} + f(x) = 0, \quad (2)$$

where $f(x)$ is an analytic function of x at $x = 0$ and

$$x(0) = x_0 \neq 0, \quad \dot{x}(0) = 0. \quad (3)$$

Here ω is the angular frequency, x_0 is the maximum amplitude and overdots denote differentiation with respect to time, t . They have examined a particular case of the function, $f(x) = x^3$ to conclude that the form of the solution (1) provides an excellent approximation to the actual solution of the equation (2) which is, however, true for $f(x) = x^3$ or odd functions. When $f(x)$ is not an odd function, the approximate periodic solution (1) for the equation of motion (2) needs a modification.

Most of the one-dimensional oscillators that occur in practical applications have functions $f(x)$ that are polynomial [2] and hence they are analytic at $x = 0$. In order to demonstrate the necessity to modify the expression (1), the well known Duffing equation will be considered in which the restoring force function, $f(x)$, is of the form [3–9]:

$$f(x) = \alpha x + \beta x^2 + \gamma x^3 + \delta \quad (4)$$

The approximate periodic solution (1) for the equation of motion (2) having $f(x)$ in the form (4) gets modified to

$$x(t) = (C + A \cos \omega t) / (1 + B \cos 2\omega t). \quad (5)$$

After the use of trigonometric identities and application of the method of harmonic balance to retain only constant terms and terms involving $\cos \omega t$, $\cos 2\omega t$ and $\cos 3\omega t$, four equations are obtained. From these equations, one obtains

$$\omega^2 = [(1 + B + \frac{1}{2} B^2)\alpha + 2C(2 + B)\beta + 3(\frac{1}{4} A^2 + C^2)\gamma] / (1 + B - \frac{1}{2} B^2), \quad (6)$$

$$C(4 - 10B^2)\alpha + [C^2(4 - 6B^2) + A^2(2 - 2B - 3B^2)]\beta \\ + C[4C^2 + (6 - 9B)A^2]\gamma + (4 - 12B^2 - \frac{9}{2} B^4)\delta = 0 \quad (7)$$

$$3B(4 - 3B) [2(2 + 2B + B^2)\alpha + 4C(2 + B)\beta + 3(A^2 + 4C^2)\gamma] \\ + 2(2 + 2B - 11B^2) [B(4 + B)\alpha + 4BC\beta + A^2\gamma] = 0 \quad (8)$$

The fourth equation for the four unknowns ω , A , B and C is provided by using the initial conditions (3) in (5) as

$$A - (1 + B)x_0 + C = 0 \quad (9)$$

The equations (7)–(9) are solved numerically using the Newton–Raphson’s iterative procedure with the initial guess values $A = x_0$; $B = \gamma A^2 / (16\alpha + 10\gamma A^2)$; and $C = [2\beta A^2(B - 1) - 4\delta] / (4\alpha + 6\gamma A^3)$.

To verify the adequacy of the proposed approximate periodic solution (5) for the Duffing equation of mixed parity, the following three cases:

- (1) $\alpha = 0$, $\beta = 0$, $\gamma = 1$, $\delta = 0$; (Mickens [4]).
- (2) $\alpha = 1$, $\beta = -0.2$, $\gamma = 0$, $\delta = -1$; (Mickens [5], Rao and Rao [6])
- (3) $\alpha = 1$, $\beta = -2.2518$, $\gamma = 2.54328$, $\delta = 0$; (Rao [9])

have been examined. The results are presented in Table 1.

It can be seen from Table 1 that in case (1) the solution (5) with $C = 0$ is good, that is, Mickens’s result. In case (2) the solution (5) with $B = 0$ is also good, whereas the solution (1) proposed by Mickens and Semwogerere [1] is 87% higher than the actual value of ω . In case (3), the solution (1) gives 12.5% higher than the actual value of ω whereas the solution (5), proposed herein, gives 0.5% lower than the actual value of ω . The approximate solution (5) proposed herein for the Duffing equation of mixed-parity in which the restoring force function, $f(x)$, is of the form (4), is found to be very close to the exact solutions as noticeable in all the above cases.

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TABLE 1

Comparison of angular frequency, ω for the amplitude, $x_0 = 3$

Case	Method of Ref. [1] equation (1)			Present study equation (5)				Exact solution ω
	A	B	ω	A	B	C	ω	
1	2.7298	-0.0901	2.5414	2.7298	-0.0901	0.0	2.5414	2.5414
2	3.0	0.0	1.0	1.2153	0.0	1.7847	0.5349	0.5349
3	2.7463	-0.0846	4.1797	2.4623	-0.0876	0.2748	3.6940	3.7138

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