

Note that the corresponding directed graph has the Hamiltonian circuit  $1 \rightarrow 6 \rightarrow 5 \rightarrow 3 \rightarrow 4 \rightarrow 2 \rightarrow 7 \rightarrow 1$  and so is strongly connected. Hence, for no permutation  $P$  does  $PAP^{-1}$  reduce. Using the algorithm described in [3] one obtains the permutations  $P = (1\ 7\ 2\ 5\ 6\ 4\ 3)$  and  $Q = (1)(2\ 3\ 6\ 7\ 5\ 4)$ . Applying  $P$  and  $Q$  to the rows and columns of  $A$ , one obtains:

$$PAQ = \begin{array}{c|ccc|cc} 1 & 2 & 0 & 0 & 0 & 0 & 0 \\ 1 & 4 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 3 & 4 & 0 & 0 & 0 & 0 \\ 3 & 0 & 2 & 2 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 4 & 0 & 0 \\ \hline 3 & 0 & 0 & 3 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 & 5 & 1 \end{array}$$

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## Missing Data Correlation Computations

By R. I. Jennrich

In correlation analysis or in any multivariate analysis based on the computation of a correlation or covariance matrix, the applied statistician often runs into the problem of missing data. To avoid complication in computing the correlation matrix, a complete observation vector is often discarded when only one or more of its components are missing. If a correlation matrix is computed by means of a standard electronic computer program, this procedure is often necessary. A large percentage of data may be thrown away when only a small percentage is missing. This note describes a modification in the standard computing scheme which eliminates this waste of data.

Let  $x_{n1}, x_{n2}, \dots, x_{np}$  denote the  $p$  components of the  $n$ th observation vector,  $n = 1, 2, \dots, N$ . It is customary to add an  $n + 1$ st component to this vector which is identically equal to one. That is  $x_{n,p+1} = 1$ . The cross product matrix

$$a_{ij} = \sum_{n=1}^N x_{ni}x_{nj} \quad i = 1, \dots, p + 1; \quad j = 1, \dots, p + 1$$

is customarily computed and the correlation matrix is computed from this matrix by using the fact that

$$a_{p+1,p+1} = N, a_{i,p+1} = \sum_{n=1}^N x_{ni}; \quad i = 1, \dots, p.$$

In addition to adding a component which is identically one to each observation vector, let us form a new vector  $c_{n1}, c_{n2}, \dots, c_{np}$  where  $c_{ni}$  is zero if the  $i$ th component of the observation vector is missing and one otherwise. Letting each element of missing data have value zero, we form the cross product matrices

$$s_{ij} = \sum_{n=1}^N x_{ni}x_{nj} \quad i, j = 1, \dots, p+1$$

$$n_{ij} = \sum_{n=1}^N c_{ni}c_{nj} \quad i, j = 1, \dots, p.$$

The means  $m_i$ , covariances  $v_{ij}$ , and correlations  $r_{ij}$  are computed from these matrices by the formulas

$$m_i = \frac{1}{n_{ii}} s_{i,p+1}$$

$$v_{ij} = \frac{1}{n_{ij}} s_{ij} - m_i m_j$$

$$r_{ij} = \frac{v_{ij}}{\sqrt{v_{ii}} \sqrt{v_{jj}}}.$$

It should be noted that the statistical properties of these estimates will differ slightly from those computed without missing data. A discussion of some of these properties is given by S. S. Wilks [1].

A FORTRAN program for the computations described in this note is in use at the University of Wisconsin. A write-up and program deck can be obtained by writing to the author.

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1. S. S. WILKS, "Moments and distributions of estimates of population parameters from fragmentary samples," *Ann. Math. Stat.*, v. 3, 1932, p. 163.

## Polynomial Approximations to $I_0(x)$ , $I_1(x)$ and Related Functions

By F. D. Burgoyne

Hitchcock [1] gives polynomial approximations to some Bessel functions of order zero and one and to some related functions. Notable omissions from his list are any approximations to  $I_0(x)$  or  $I_1(x)$ . The following approximations may serve to fill this gap.

If we write  $I_n(x) = (2\pi x)^{-1/2} e^x F_n(x)$ , then with the maximum error stated in brackets in each case, and provided  $0 \leq t \leq 1$ ,

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