

permutations obtained are no longer random. Consider the algorithm where at the k th step, the k th object is exchanged with any one of the N objects. This transformation when applied N times produces N^N equiprobable mappings of a particular permutation into the set of all permutations of N objects. But there are only $N!$ members in the set and N^N is not divisible by $N!$ if $N > 2$, so that each of the $N!$ permutations is not equiprobable.

The pairwise exchange method is equally well suited for the generation of permutations, combinations, or arrangements. A random combination or arrangement of p objects among N is obtained by performing only p exchanges, the result being the p first objects so generated.

Computing Center
California Institute of Technology
Pasadena, California 91109

1. B. JANSSON, *Random Number Generators*, V. Pettersons Bokindustri Aktiebolag, Stockholm, 1966, pp. 189–191.

2. D. H. LEHMER, "The machine tool of combinatorics," *Applied Combinatorial Mathematics*, edited by E. Beckenbach, Wiley, New York, 1964, pp. 19–23. MR 30 #4687.

On Finding the Disc of Minimum Radius Containing a Given Set of Points*

By L. J. Bass and S. R. Schubert

Recently many combinatorial problems have been found to be amenable to computer solution. This report presents a description of one such problem and its solution.

Let E be a given set of points of finite cardinality in the plane \mathcal{R}^2 . The problem is to determine the disc D_{\min} of minimum radius such that $E \subset D_{\min}$.

This is a nontrivial problem. The centroid of E gives no information at all. A complete analytic solution appears extremely difficult, since probably new concepts are required. Moreover, any essentially exhaustive procedure formulated for machine solution is only feasible when E has very small cardinality. However, consideration of a few simple geometrical theorems quickly places the problem in a much more tractable setting.

Definition. Let $E \subset \mathcal{R}^2$ be given as above. The convex hull of the extreme points of E is that convex polygon P such that $E \subset P$ and the vertices of P are points of E . These vertices are called the extreme points of E .

THEOREM 1. *The extreme points of E completely determine D_{\min} .*

Proof. This is clear since $E \subset P \subset D_{\min}$.

THEOREM 2. *There are at least two extreme points of E which are on the boundary of D_{\min} . Moreover, if there are exactly two points, then these are, in fact, the endpoints*

Received May 9, 1966. Revised April 24, 1967.

* Contract No. AFO4(695)-669.

of the diameter of D_{\min} which coincides with the point-set diameter of E .

Proof. The first statement of the theorem is clear. Let P_1, P_2 be the extreme points on the boundary of D_{\min} , P_1P_2 the associated line segment, and suppose that P_1P_2 is not the diameter of D_{\min} . Now consider the pencil of circles through P_1 and P_2 . There must exist in this pencil a circle of maximum radius which contains a point of E , say P_3 , different from P_1 and P_2 . Obviously the circle determined by P_1, P_2, P_3 contains E and has a radius strictly less than the radius of D_{\min} . Hence, P_1P_2 is the diameter of D_{\min} and clearly must coincide with the point-set diameter of E .

THEOREM 3. *Let α be the point-set diameter of E . Then the radius R of D_{\min} is bounded below by $\alpha/2$ and bounded above by $\alpha/\sqrt{3}$.*

Proof. Clearly R is bounded from below by $\alpha/2$. Now consider a circle C with an inscribed equilateral triangle T determined by the three points a, b, c and with side α . α is also the point-set diameter of the set $\{a, b, c\}$. The radius r of C is $\alpha/\sqrt{3}$. Now let T' be another triangle inscribed in C , determined by a', b', c' and not equilateral; let α' be the point-set diameter of $\{a', b', c'\}$. Then $r = \alpha/\sqrt{3} < \alpha'/\sqrt{3}$.

The computer algorithm for finding D_{\min} is based on determining the set of extreme points of E . This is done in the following manner. An initial set of extreme points is selected on the basis of extreme values of the coordinates, that is, the two points with the largest and smallest x -coordinates and the two points with the largest and smallest y -coordinates. This set consists of two, three, or four points. The general situation is pictured in Fig. 1. P_1, P_2, P_3, P_4 are the points of E with extreme values of the coordinates, and the polygon determined by these points is the first approximation to the convex hull of E . The set E is contained in the rectangle a, b, c, d . The designated quadrants contain the points of E eligible for refining the convex hull around the reference segments $P_1P_2, P_2P_3, P_3P_4, P_4P_1$.

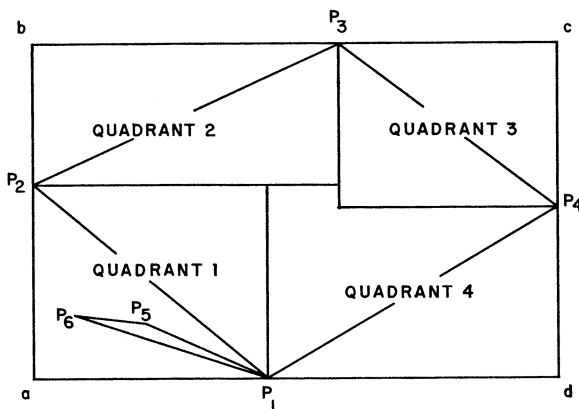


FIGURE 1. First Approximation to the Hull with a False Extreme Point.

For any line segment P_iP_j , define $s(P_iP_j)$ to be its slope. The procedure begins by constructing the portion of the convex hull in the quadrant with diagonal P_1P_2 . This is done by ordering the points according to increasing values of the y -coordinates and initially comparing the slopes $s(P_1P_i)$ with the reference slope $s(P_1P_2)$, $i = 5, 6, 7, \dots$. If $s(P_1P_i) \geq s(P_1P_2)$, P_i is a candidate for an extreme

point; if $s(P_1P_i) < s(P_1P_2)$, P_i is never considered again throughout the entire process. As soon as a candidate P_i is found, the reference slope is changed to $s(P_iP_2)$; thus if, for $j > i$, $s(P_iP_2) \leq s(P_iP_j)$, P_j is an extreme-point candidate. Now, if $s(P_1P_i) < s(P_iP_j)$, P_i is a false extreme point since the slopes of the edges of the convex hull must be monotonically nonincreasing as one proceeds clockwise around the hull. The new reference slope is then P_jP_2 . For example, as pictured in Fig. 1, P_5 is a fake extreme point that would be discarded. This process proceeds through all four quadrants.

Once the set of extreme points has been found, the point-set diameter α of E is determined among all pairs of extreme points. If the disc with diameter corresponding to the point-set diameter contains E , the procedure terminates; if not, the discs corresponding to all triples of extreme points are examined. If the radius of a disc exceeds the bounds specified in Theorem 3, it is discarded. Among the remainder, D_{\min} is determined by considering the discs in the order of increasing radius and seeing whether or not they contain E .

The type of geometric approach described in this note was selected over various other approaches specifically because the particular application for which it was used required knowledge of the convex hull of E as well as D_{\min} .

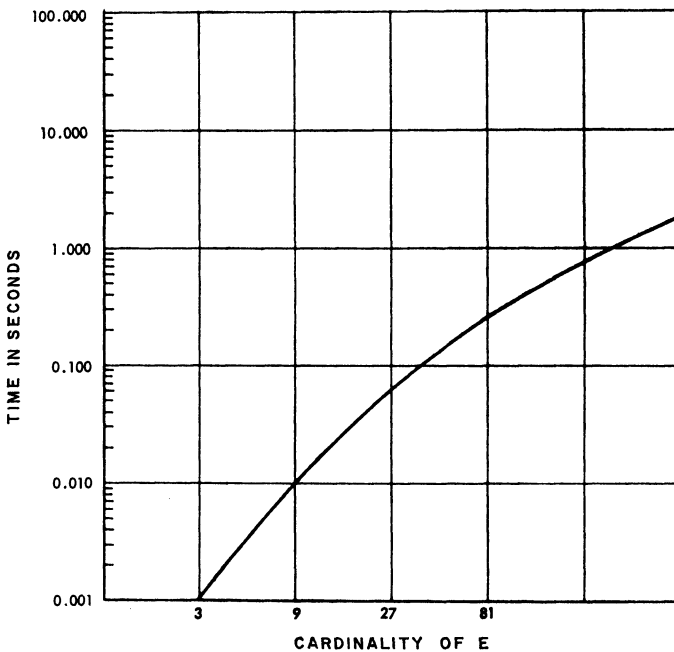


FIGURE 2. Results of Timing Studies.

The algorithm was programmed for the IBM 7040-7094II Direct Coupled System. The results of a series of timing studies are displayed in Figure 2.