

Reducing a Matrix to Hessenberg Form

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Abstract. It has been an open problem whether the reduction of a matrix to Hessenberg (almost triangular) form by Gaussian similarity transformations is numerically stable [2, p. 364]. We settle this question by exhibiting a class of matrices for which this process is unstable.

As a major step towards the numerical solution of the non-Hermitian algebraic eigenvalue problem, a matrix is usually first reduced to Hessenberg (almost triangular) form either by a sequence of Householder similarity transformations, [2, p. 347] or else by some form of Gaussian elimination [2, p. 353]. In practice, the latter process is favored because it requires fewer arithmetic operations. However, it is known that Householder's reduction is numerically stable [2, p. 350], while it has been an open problem whether Gaussian elimination is stable [2, p. 364]. We settle this question by exhibiting a class of matrices for which Gaussian elimination is unstable.

The column-by-column reduction of an n by n matrix $A = (a_{ij})$ to upper Hessenberg form by Gaussian elimination produces a sequence of similarity transforms

$$A_k = (G_k^{-1}P_k^{-1})A_{k-1}(P_kG_k), \quad k = 1, 2, \dots, n-2,$$

of $A_0 = A$. $G_k^{-1} = (\bar{g}_{ij}^{(k)})$ differs from the identity matrix only in the elements $\bar{g}_{i,k+1}^{(k)}$, $i = k+2, k+3, \dots, n$, which are chosen such that A_k has zeros in positions $(k+2, k)$, $(k+3, k)$, \dots , (n, k) . The permutation matrices P_k are chosen such that

$$|\bar{g}_{i,k+1}^{(k)}| \leq 1, \quad (i = k+2, k+3, \dots, n).$$

Wilkinson [2, p. 364] points to the danger of potential worsening of the condition of the eigenvalues caused by large elements in the matrices

$$F_k^{-1} = (\bar{f}_{ij}^{(k)}) = (G_k^{-1}P_k^{-1})(G_{k-1}^{-1}P_{k-1}^{-1}) \dots (G_1^{-1}P_1^{-1})$$

It is implicit in [2] that the largest element of F_k^{-1} is bounded in magnitude by 2^{k-1} ; the theorem below shows this bound to be sharp and the example illustrates the consequences of this fact. The proof of the theorem uses a construction analogous to that of [2, p. 212].

THEOREM. *There exist matrices for which*

$$\max_{i,j} |\bar{f}_{ij}^{(k)}| = 2^{k-1}.$$

Proof. Let

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$$A = \begin{bmatrix} a_1 & a_2 & \cdot & \cdot & \cdot & a_{n-1} & a_n \\ & 1 & & & & & \\ -1 & 1 & & & 0 & & \\ & \cdot & & \cdot & & & \\ & \cdot & 0 & & \cdot & & \\ & \cdot & & & & \cdot & \\ -1 & & & & & & 1 \end{bmatrix}$$

where a_1, a_2, \dots, a_n are arbitrary. Then, for $P_k = I, k = 1, 2, \dots, n - 2, \bar{g}_{k+2, k+1}^{(k)} = \bar{g}_{k+3, k+1}^{(k)} = \dots = \bar{g}_{n, k+1}^{(k)} = 1$ and $\max |\bar{f}_{ij}^{(k)}| = 2^{k-1}$.

While the following example does not quite achieve the bound 2^{k-1} , it illustrates the effect of large elements of F_k^{-1} .

Example. Consider the 6 by 6 matrix

$$B = \begin{bmatrix} 0 & 1 & 1 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 & 0 & -1 \\ -1 & 1 & 0 & 0 & 0 & -1 \\ -1 & 0 & 1 & 0 & 0 & -1 \\ -1 & 0 & 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & -\frac{1}{2} & \frac{1}{2} & 0 \end{bmatrix}$$

whose eigenvalues $\lambda_i(B)$ are given to five figures in the table. (The calculations were performed on a GE645 computer by programs given in [1].) We also give approximate values of the condition numbers

$$s_i(B) = \frac{\|y_i^H\| \|x_i\|}{|y_i^H x_i|},$$

where y_i^H and x_i are row- and column-eigenvectors of B . Since no s_i is large, all eigenvalues of B are insensitive to small perturbations in the elements of B . After column-reducing B to upper Hessenberg form we obtain

$$H = B_4 = \begin{bmatrix} 0 & -2 & -1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 1 & -1 \\ 0 & 1 & 0 & 0 & 2 & -2 \\ 0 & 0 & 1 & 0 & 4 & -4 \\ 0 & 0 & 0 & 1 & 8 & -8 \\ 0 & 0 & 0 & 0 & 8\frac{1}{2} & -8 \end{bmatrix}.$$

Since H is similar to B , its eigenvalues $\lambda_i(H)$ agree with those of B . However, the transformed condition numbers

$$s_i(H) = \frac{\|y_i^H F_4\| \|F_4^{-1} x_i\|}{|y_i^H x_i|}$$

indicate considerably greater sensitivity of the eigenvalues to perturbations in the elements of H .

TABLE. Numerical Results for the Example.

$\lambda_i(B) = \lambda_i(H)$	$s_i(B)$	$s_i(H)$	$\lambda_i(H')$
1.0000	1.2	7.1	2.2725
-1.1869	1.4	3.8	-1.8652
.47473 ± 1.4373i	1.9	2.6	.31126 ± 1.4433i
-.38127 ± 1.2286i	1.7	4.0	-.51492 ± .77502i

Suppose now that the reduction to Hessenberg form was carried out in truncated 4-bit arithmetic. (This example can be generalized to n dimensions and $(n - 2)$ -bit arithmetic.) The reduced matrix becomes

$$H' = \begin{bmatrix} 0 & -2 & -1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 1 & -1 \\ 0 & 1 & 0 & 0 & 2 & -2 \\ 0 & 0 & 1 & 0 & 4 & -4 \\ 0 & 0 & 0 & 1 & 8 & -8 \\ 0 & 0 & 0 & 0 & 8 & -8 \end{bmatrix}$$

whose (6, 5)-element differs slightly from the corresponding element of H . Due to sensitivity to this difference, the eigenvalues $\lambda_i(H')$ show little resemblance to those of B .

We have shown that there exist matrices which cannot be stably reduced to Hessenberg form by means of Gaussian elimination in finite precision arithmetic. Householder transformations, however, provide unconditional stability.

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1. J. M. VARAH, *The Computation of Bounds for the Invariant Subspaces of a General Matrix Operator*, Tech. Report No. CS66, Stanford University, Stanford, Calif., 1967.
2. J. H. WILKINSON, *The Algebraic Eigenvalue Problem*, Clarendon Press, Oxford, 1965. MR 32 #1894.