

Supplement to The Convergence of Galerkin Approximation Schemes for Second-Order Hyperbolic Equations With Dissipation

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2. Convergence Estimates for Semi-discrete Approximations

PROPOSITION 1. If $U(t)$ satisfies (1.6) and $U_h(t)$ satisfies (1.10) with $U_h(0) = P_h U_0$, $U_0 \in H^{q+1}(\Omega) \times H^q(\Omega)$ then

$$\|U(t) - U_h(t)\|_0 \leq c(t^*, \alpha) h^{q-1} \|U_0\|_q, \quad 1 \leq q \leq r \\ 0 \leq t \leq t^*.$$

Proof. Firstly for $q=1$, we have

$$\begin{aligned} \|U(t) - U_h(t)\|_0 &\leq \|U(t)\|_0 + \|U_h(t)\|_0 \\ &\leq \|U_0\|_0 + \|P_h U_0\|_0 \\ &\leq 2\|U_0\|_0 \end{aligned}$$

by (1.4), (1.12) and since P_h is the projection with respect to $(\cdot, \cdot)_0$.

For $2 \leq q \leq r$, we write

$$U(t) - U_h(t) = (U(t) - P_h U(t)) + (P_h U(t) - U_h(t)).$$

By (1.16),

$$\begin{aligned} \|U(t) - P_h U(t)\|_0 &\leq ch^{q-1} \|U(t)\|_{q-1} \\ &\leq ch^{q-1} \|U_0\|_{q-1} \\ &\leq ch^{q-1} \|U_0\|_q, \end{aligned}$$

we have to show that

$$\|P_h U(t) - U_h(t)\|_0 \leq ch^{q-1} \|U_0\|_q.$$

From the identity

$$\mathbf{j}_h D_t P_h U(t) + P_h U(t) + \alpha T P_h U(t) = (\mathbf{j}_h - \mathbf{j}) D_t U(t) + \mathbf{j}_h (P_h - 1) D_t U(t),$$

it follows that

$$\begin{aligned} \mathbf{j}_h D_t P_h U(t) + P_h U(t) + \alpha T P_h U(t) &= (\mathbf{j}_h - \mathbf{j}) D_t U(t) + \mathbf{j}_h (P_h - 1) D_t U(t) \\ &\quad + (P_h - 1) U(t) + \alpha T (P_h - 1) U(t) \\ &= (\mathbf{j} - \mathbf{j}_h) \mathbf{U}(t) + \mathbf{j}_h (1 - P_h) \mathbf{U}(t) + (P_h - 1) U(t) \\ &\quad + \alpha ((\mathbf{j} - \mathbf{j}_h) U(t) + \mathbf{j}_h (1 - P_h) U(t) + (P_h - 1) U(t)) \\ &= \rho_h(t) + \alpha (\mathbf{j} I - \mathbf{j}_h P_h I + T(P_h - 1)) U(t), \end{aligned}$$

where $\rho_h(t)$ is as in [5], (2.3).

Simplification of the last factor yields

$$\mathbf{j}_h D_t P_h U(t) + P_h U(t) + \alpha T P_h U(t) = \rho_h(t) + \alpha ((T - T_h) P_h^* U, 0)^T.$$

$U_h(t)$ satisfies

$$\mathbf{j}_h D_t U_h(t) + U_h(t) + \alpha T_h U_h(t) = 0, \quad U_h(0) = P_h^* U_0,$$

and setting $E_h^*(t) = P_h U(t) - U_h(t)$, we obtain

$$\begin{aligned} \mathbf{j}_h D_t E_h^*(t) + E_h^*(t) &= \rho_h(t) + \alpha ((T - T_h) P_h^* U, 0)^T - \alpha T_h U(t) + \alpha T_h \|U_h\|_h \\ &= \rho_h(t) + \alpha T_h (\dot{U}_h - P_h^* U), C^{-1}. \end{aligned}$$

$$E_h^*(0) = 0.$$

We form the energy inner product with $D_t E_h^*(t)$, and use the skew-adjointness of \mathbf{j}_h to obtain

$$\begin{aligned} \langle (E_h^*(t), D_t E_h^*(t)) \rangle_O &= \langle (\rho_h(t), D_t E_h^*(t)) \rangle_O + \alpha \langle ([T_h \dot{U}_h - P_h^* \dot{U}], \mathbf{o}), D_t E_h^*(t) \rangle_O \\ \text{i.e. } \frac{1}{2} \frac{d}{dt} \|E_h^*(t)\|_O^2 &= \langle (\rho_h(t), D_t E_h^*(t)) \rangle_O + \alpha \langle (T_h (\dot{U}_h - P_h^* \dot{U}), P_h^* \dot{U} - \dot{U}_h) \rangle_O. \end{aligned}$$

For the final term here we have

$$\begin{aligned} \alpha \langle (T_h (\dot{U}_h - P_h^* \dot{U}), P_h^* \dot{U} - \dot{U}_h) \rangle_O &= \alpha (\dot{U}_h - P_h^* \dot{U}, P_h^* \dot{U} - \dot{U}_h) \\ &= \alpha (\dot{U}_h - P_h^* \dot{U}, P_h^* \dot{U} - \dot{U}_h) + \alpha (\dot{U}_h - P_h^* \dot{U}, P_h^* \dot{U} - P_h^* \dot{U}) \\ &\leq \alpha (\dot{U}_h - P_h^* \dot{U}, P_h^* \dot{U} - P_h^* \dot{U}), \end{aligned}$$

so that

$$\frac{d}{dt} \|E_h^*(t)\|_O^2 \leq 2 \langle (\rho_h(t), D_t E_h^*(t)) \rangle_O + 2\alpha (\dot{U}_h - P_h^* \dot{U}, P_h^* \dot{U} - P_h^* \dot{U}).$$

Exactly as in [5] Proposition 1, or [11] Theorem 2.1, we derive the inequality

$$\begin{aligned} (2.1) \quad \frac{1}{2} \sup_{0 \leq t \leq T} \|E_h^*(t)\|_O^2 &\leq 4 \sup_{0 \leq t \leq T} \{ \|U_h(t)\|_O^2 + (t^*)^2 \|D_t U_h(t)\|_O^2 \\ &\quad + \alpha \sup_{0 \leq t \leq T} \{ \frac{1}{\alpha} \|\dot{U}_h - P_h^* \dot{U}\|_O^2 + 4\alpha (t^*)^2 \|P_h^* \dot{U} - P_h^* \dot{U}\|_O^2 \} \}. \end{aligned}$$

$$\|U_h(t)\|_O \leq c h^{q-1} \|U_0\|_{q-1}$$

from [5], Proposition 1.

By (1.2), we have

$$\begin{aligned} D_t \rho_h(t) &= \{(\mathbf{j}_h - \mathbf{j}) \wedge^2 U(t) + \mathbf{j}_h (P_h - 1) \wedge^2 U(t) + (1 - P_h) \wedge U(t) \\ &\quad + \alpha ((\mathbf{j}_h - \mathbf{j}) \wedge U(t) + \mathbf{j}_h P_h - 1) \wedge U(t) + (1 - P_h) \wedge U(t) \} \\ &= [D_t \rho_h(t)]_I + \alpha [D_t \rho_h(t)]_{II}. \end{aligned}$$

The first term is exactly as in [5] and therefore

$$\|[\mathbf{D}_t P_h(t)]_1\|_0 \leq c h^{q-1} \|U_0\|_q.$$

For the second term, using (1.16), (1.17) and (1.18), we obtain

$$\begin{aligned} \|\mathbf{D}_t P_h(t)\|_0 &\leq \|(J_h - J) \wedge U(t)\|_0 + \|(P_h - I) \wedge U(t)\|_{-1,h} \\ &\quad + \|(I - P_h) \wedge U(t)\|_0 \\ &\leq ch^{q-1} \|U(t)\|_{q-1} \\ &= ch^{q-1} \|[O, \dot{U}(t)]\|_{q-1} \\ &\leq ch^{q-1} \|U(t)\|_{q-1} \\ &\leq ch^{q-1} \|U_0\|_{q-1} + \alpha ch^{q-1} \|U_0\|_{q-1} \\ &\leq (P_h^1 - P_h^0)U(t) + (P_h^0 - I)U(t) + \alpha P_h^0 U(t) = J_h^0(J_h - J)D_t U(t). \end{aligned}$$

Combining the above inequalities, we obtain

$$\begin{aligned} \|\mathbf{D}_t P_h(t)\|_0 &\leq ch^{q-1} \|U_0\|_q + \alpha ch^{q-1} \|U_0\|_{q-1} \\ &\leq c(\alpha)h^{q-1} \|U_0\|_q. \end{aligned}$$

For the remaining terms of (2.1) we have the estimates

$$\begin{aligned} \|\dot{U}_h - P_h^0 U(t)\|_0 &\leq \|\mathbf{E}_h^*(t)\|_0 \\ \text{and } \|(P_h^1 - P_h^0)U(t)\|_0 &\leq \|(P_h \dot{U} - \dot{U})(t)\|_0 + \|\dot{U} - P_h^0 \dot{U}(t)\|_0 \\ &\leq ch^{q-1} \|\dot{U}(t)\|_{q-1} \\ &\leq ch^{q-1} \|U(t)\|_{q-1} \\ &\leq ch^{q-1} \|U_0\|_{q-1}. \end{aligned}$$

Therefore from (2.1)

$$\sup_{t \in T^*} \|\mathbf{E}_h^*(t)\|_0^2 \leq c(\alpha, t^*) h^{2(q-1)} \|U_0\|_q^2 + \frac{1}{2} \sup_{t \in T^*} \|\mathbf{E}_h^*(t)\|_0^2$$

For the second term, using (1.16), (1.17) and (1.18), we obtain

$$\|\mathbf{E}_h^*(t)\|_0 \leq c(\alpha, t^*) h^{q-1} \|U_0\|_q,$$

and the proposition has been established.

PROPOSITION 2. If $U(t)$ satisfies (1.6) and $U_h(t)$ satisfies (1.10) with $U_h(0) = P_h U_0$ and $U_0 \in H^{q+1}(\Omega) \times H^0(\Omega)$, $1 \leq q \leq r$, then

$$\|U(t) - U_h(t)\|_{-p,h} \leq c(t^*, \alpha) h^{p+q-1} \|U_0\|_q, \quad 1 \leq p \leq r-1.$$

Proof. As in the previous proposition, we write

$$J_h D_t U(t) + U(t) + \alpha T U(t) = (J_h - J) D_t U(t),$$

so that

$$J_h^{p+1} D_t U(t) + J_h^p U(t) + \alpha J_h^p T U(t) = J_h^p (J_h - J) D_t U(t).$$

We also have

$$J_h^{p+1} D_t U_h(t) + J_h^p U_h(t) + \alpha J_h^p T_h U_h(t) = 0.$$

so that with

$$E_h(t) = U(t) - U_h(t),$$

it follows that

$$\begin{aligned} J_h^{p+1} D_t E_h(t) + J_h^p E_h(t) &= J_h^p (J_h - J) D_t U(t) - \alpha J_h^p T_h U_h(t) \\ &= J_h^p (J - J_h) U(t) + \alpha J_h^p (J - J_h) U(t) + \alpha J_h^p U(t) \\ &\quad + \alpha J_h^p T_h U_h(t) \\ &= J_h^p (J - J_h) U(t) + \alpha J_h^p [T_h (\dot{U}_h - \dot{U})]^\top. \end{aligned}$$

and, as in the proof of Proposition 1,

$$\begin{aligned} \sigma_h^1(t) &= (J - J_h) \wedge U(t), \\ \sigma_h^2(t) &= [T_h(\dot{u}_h - \dot{u}), \varrho]^\top, \\ \text{and form the energy inner product with } &J_h^P t E_h(t). \end{aligned}$$

Then

$$\frac{1}{2} \frac{d}{dt} \|J_h^P t E_h(t)\|_0^2 = (\langle J_h \sigma_h^1(t), J_h^P t E_h(t) \rangle_0 + \alpha(\langle J_h^P \sigma_h^2(t), J_h^P t E_h(t) \rangle)_0$$

The latter term is treated as follows:

$$\begin{aligned} \langle \langle J_h^P \sigma_h^2(t), J_h^P t E_h(t) \rangle \rangle_0 &= (-1)^p (\langle J_h^{2p} \sigma_h^2(t), D_t E_h(t) \rangle)_0 \\ &= (\langle T_h^{p+1}(\dot{u}_h - \dot{u}), 0 \rangle^\top, (\dot{u} - \dot{u}_h, D_t \dot{u} - D_t \dot{u}_h)^\top)_0 \\ &\quad + \langle \langle T_h^{p+1}(\dot{u}_h - \dot{u}), \dot{u} - \dot{u}_h \rangle \rangle_0 \\ &= \langle \langle T_h^{p+1}(\dot{u}_h - \dot{u}), \dot{u} - \dot{u}_h \rangle \rangle_0 \\ &= \alpha(T_h^{p+1}(\dot{u}_h - \dot{u}), P_h^0 \dot{u} - \dot{u}_h) + \alpha(T_h^{p+1}(\dot{u}_h - \dot{u}), \dot{u} - P_h^0 \dot{u}) \\ &= (T_h^p(\dot{u}_h - \dot{u}), P_h^0 \dot{u} - \dot{u}_h) + \alpha(T_h^{p+1}(\dot{u}_h - \dot{u}), P_h^1(\dot{u} - P_h^0 \dot{u})) \\ &= (T_h^p(\dot{u}_h - \dot{u}), \dot{u} - \dot{u}_h) + (T_h^p(\dot{u}_h - \dot{u}), P_h^1 \dot{u} - P_h^1 P_h^0 \dot{u}) \\ &\leq (\dot{u}_h - \dot{u}, P_h^1 \dot{u} - P_h^1 P_h^0 \dot{u})_{-p, h} \\ &= (\dot{u}_h - \dot{u}, P_h^1 \dot{u} - P_h^1 P_h^0 \dot{u})_{-p, h} \end{aligned} \tag{2.2}$$

since $P_h^1 P_h^0 = P_h^0$.

$$(\alpha(P_h^1 P_h^0 u, v)) = \alpha(P_h^1 P_h^0 u, P_h^1 v) = \alpha(P_h^0 u, P_h^1 v) = \alpha(P_h^0 u, v), \quad v \in H^1(\Omega).$$

Then

$$\begin{aligned} \frac{d}{dt} \|E_h(t)\|_{-p, h}^2 &\leq 2(\langle J_h^{p+1}(t), J_h^P D_t E_h(t) \rangle)_0 + 2\alpha(\dot{u}_h - \dot{u}, (P_h^1 - P_h^0) \dot{u})_{-p, h}, \\ &\leq c h^{p+q-1} \|U_0\|_q. \end{aligned}$$

Therefore, since $\dot{u}_h - \dot{u} \in -p, h \leq \|E_h(t)\|_{-p, h}$ we have

$$\begin{aligned} \sup_{0 \leq t \leq t^*} \|E_h(t)\|_{-p, h} &\leq c(t^*) \left(\sup_{0 \leq t \leq t^*} \|\sigma_h^1(t)\|_{-p, h} + \|D_t \sigma_h^1(t)\|_{-p, h} \right) \\ &\quad + \alpha \sup_{0 \leq t \leq t^*} \left(\frac{1}{4\pi} \|\dot{u}_h - \dot{u}\|_{-p, h}^2 + 4\alpha((P_h^1 - P_h^0) \dot{u})_{-p, h} \right). \end{aligned} \tag{2.3}$$

which may be compared with (2.11) of [5], and

$$\|\sigma_h^1(t)\|_{-p, h} \leq c h^{p+q-1} \|U_0\|_q.$$

Also

$$\begin{aligned} D_t \sigma_h^1(t) &= (J_h - J) h^2 U(t) + \alpha(J_h - J) T(t) \\ &= (D_t \sigma_h^1(t))_1 + \alpha(D_t \sigma_h^1(t))_{11}. \end{aligned}$$

The first term here corresponds to $D_t \sigma_h^1(t)$ of [5], Proposition 2, and so

$$\|D_t \sigma_h^1(t)\|_{-p, h} \leq c h^{p+q-1} \|U_0\|_q,$$

while

$$\begin{aligned} \|(D_t \sigma_h^1(t))_{11}\|_{-p, h} &\leq c h^{p+q-1} \|U(t)\|_{q-2} \\ &\leq c h^{p+q-1} \|U(t)\|_{q-2} \\ &\leq c h^{p+q-1} \|U_0\|_q. \end{aligned}$$

As in [5], we have the estimate

$$\|E_h(0)\|_{-p,h} \leq ch^{p+q-1} \|U_0\|_q.$$

Finally

$$\begin{aligned}
& \|(\mathcal{P}_h^1 - \mathcal{P}_h^0)u\|_{-p,h} \leq \|\mathcal{P}_h^1 u - \mathcal{U}_{-p,h} + \mathcal{P}_h^0 u - \mathcal{U}_{-p,h}\|_{-p,h} \\
& \leq c(\|\mathcal{P}_h^1 u - \mathcal{U}_{-p,h}\| + h\|\mathcal{P}_h^1 u - \mathcal{U}_{-p,h}\|_0) \\
& \quad + \|P_h^0 u - \mathcal{U}_{-p,h}\|_0 + h\|\mathcal{P}_h^0 u - \mathcal{U}_{-p,h}\|_0 \\
& \leq ch^{p+q-1} \|u(t)\|_{q-1} \\
& \leq ch^{p+q-1} \|U(t)\|_{q-1} \\
& \leq ch^{p+q-1} \|U_0\|_q.
\end{aligned} \tag{2.4}$$

and the proposition has been established.

Remark. The optimal L²-estimate for $u_h(t) - u(t)$ follows from the

case p=1:

$$\|u(t) - u_h(t)\|_0 \leq c(t^*, \alpha) h^r \|U_0\|_r.$$

Propositions 1 and 2 and (1.18) yield our main result.

THEOREM 1. If $U(t)$ is the solution of (1.6) and $U_h(t)$ is the solution

of (1.10) with $U_h(0) = \mathcal{P}_h U_0$, $U_0 \in \mathbb{H}^{q+1}(\Omega) \times \mathbb{H}^q(\Omega)$, $1 \leq q \leq r$, then for

$0 \leq t \leq t^*$,

$$\|U(t) - U_h(t)\|_{-p} \leq c(t^*, \alpha) h^{p+q-1} \|U_0\|_q,$$

$$0 \leq p \leq r-1.$$

We refer the reader to the corresponding result for the non-dissipative

case, Theorem 1 and Remarks 1 and 2 of [5].

4. Estimates for higher order time derivatives

THEOREM 4. Assume $U_0 \in \mathbb{H}^{s+q+1}(\Omega) \times \mathbb{H}^{s+q}(\Omega)$, $s \geq 1$, $1 \leq q \leq r$.

Then

$$\|\mathcal{D}_t^s U(t) - \mathcal{D}_t^s U_h(t)\|_{-p} \leq c(t^*, \alpha) h^{p+q-1} \|U_0\|_{s+q}, \quad 0 \leq p \leq r-1.$$

Proof. The energy estimate is derived first. We have

$$\begin{aligned}
& \mathcal{D}_t^s U(t) - \mathcal{D}_t^s U_h(t) = (-1)^s (\Lambda_\alpha^s U(t) - \Lambda_{\alpha,h}^s U_h(t)) \\
& = (-1)^s (\Lambda_\alpha^s U(t) - \Lambda_{\alpha,h} J_\alpha^2 \Lambda_\alpha^{s+1} U(t)) \\
& \quad + (-1)^s (\Lambda_{\alpha,h} J_\alpha^2 \Lambda_\alpha^{s+1} U(t) - \Lambda_{\alpha,h}^s U_h(t)) \\
& = (-1)^s \{E_h^{**}(t) + E_h^*(t)\}.
\end{aligned}$$

Now

$$\begin{aligned}
& \|E_h^{**}(t)\|_0 = \|(\Lambda_\alpha^s U(t) - \Lambda_{\alpha,h} J_\alpha^2 \Lambda_\alpha^{s+1} U(t))\|_0 \\
& \quad = \|(\Lambda_\alpha - \Lambda_{\alpha,h} J_\alpha^2 \Lambda_\alpha^{s+1} U(t))\|_0,
\end{aligned} \tag{4.4}$$

and one can show that

$$\Lambda_\alpha - \Lambda_{\alpha,h} J_\alpha^2 \Lambda_\alpha^{s+1} U(t) = J - \Lambda_h J_h^2 + \alpha \begin{bmatrix} I - I_h & 0 \\ 0 & 0 \end{bmatrix}.$$

Therefore,

$$\|E_h^{**}(t)\|_0 \leq \|(J - \Lambda_h J_h^2) \Lambda_\alpha^{s+1} U(t)\|_0 + \alpha \|(I - I_h)(\Lambda_\alpha^{s+1} U(t))\|_0.$$

Here $(Z)^I$ denotes the first component of $Z = [(Z)^I, (Z)^{II}]^T$. From (4.5) of [5] and our estimate (4.3), we have immediately that

$$\begin{aligned}
& \|(J - \Lambda_h J_h^2) \Lambda_\alpha^{s+1} U(t)\|_0 \leq c(h^{-1}) \|U(t)\|_{q-2} \\
& \leq c(\alpha) h^{q-1} \|U(t)\|_{s+q-1} \\
& \leq c(\alpha) h^{q-1} \|U_0\|_{s+q-1}.
\end{aligned}$$

SUPPLEMENT

Also, by (1.9) and (4.3),

$$\begin{aligned}
 & \| \Gamma(T - T_h)(\Lambda_\alpha^{s+1} U(t))^\top, 0^\top \|_0 = \| (T - T_h)(\Lambda_\alpha^{s+1} U(t)) \|_{L^1} \\
 & \leq c h^{q-1} \| (\Lambda_\alpha^{s+1} U(t)) \|_{L^{q/2}} \\
 & \leq c h^{q-1} \| (\Lambda_\alpha^{s+1} U(t)) \|_{L^{q/3}} \\
 & \leq c(\alpha) h^{q-1} \| U(t) \|_{L^{s+q/2}} \\
 & \leq c(\alpha) h^{q-1} \| U(t) \|_{L^{s+q-1}},
 \end{aligned}$$

so that

$$(4.5) \quad \| E_h^{**}(t) \|_0 \leq c(\alpha) h^{q-1} \| U \|_{L^{s+q-1}}.$$

Using (4.1), we can write

$$\begin{aligned}
 J_{\alpha,h} D_t E_h^*(t) + E_h^*(t) &= (\Lambda_{\alpha,h} - J_{\alpha,h}) D_t \Lambda_\alpha^s U(t) + J_{\alpha,h} D_t (\Lambda_{\alpha,h} \Lambda_\alpha^{s+1} U(t) \\
 &\quad - \Lambda_\alpha^s U(t)) + (\Lambda_{\alpha,h} \Lambda_\alpha^{s+1} U(t) - \Lambda_\alpha^s U(t)) \\
 &\equiv \tilde{\rho}_h(t), \\
 \text{and} \quad E_h^*(0) &= \Lambda_{\alpha,h} \Lambda_\alpha^{s+1} U_0 - \Lambda_{\alpha,h} \Lambda_\alpha^{s+1} U_0 \\
 &= 0.
 \end{aligned}$$

Since $J_{\alpha,h} = J_h + oJ_h^*$, we have

$$J_h D_t E_h^*(t) + E_h^*(t) = \tilde{\rho}_h(t) - \alpha T_h^* D_t E_h^*(t)$$

$$E_h^*(0) = 0.$$

Taking the energy inner product with $D_t E_h^*(t)$ and using the skew-adjointness of J_h yields

$$\frac{1}{2} \frac{d}{dt} \| E_h^*(t) \|_0^2 = \langle (\tilde{\rho}_h(t), D_t E_h^*(t)) \rangle_0 - \alpha \langle (T_h^* D_t E_h^*(t), D_t E_h^*(t)) \rangle_0.$$

Now, for any $Z \in S_h^r(\Omega) \times L^2(\Omega)$,

$$\begin{aligned}
 \langle (T_h^* Z, Z) \rangle_0 &= \langle (T_h(Z)^\top, Z), (Z^\top, Z) \rangle_0 \\
 &= \alpha \langle T_h(Z)^\top, Z \rangle_0 \\
 &= \langle (Z)^\top, (Z) \rangle_0 \\
 &\geq 0.
 \end{aligned}$$

The term

$$\begin{aligned}
 D_t E_h^*(t) &= \Lambda_{\alpha,h}^{s+1} U_h(t) - \Lambda_{\alpha,h} \Lambda_\alpha^{s+2} U(t) \\
 &= \Lambda_{\alpha,h}^{s+1} U_h(t) - J_{\alpha,h} \Lambda_\alpha^{s+2} U(t) \\
 &\in S_h^r(\Omega) \times L^2(\Omega).
 \end{aligned}$$

In fact, for $U_0 \in \dot{H}^{s+q+1}(\Omega) \times \dot{H}^{s+q}(\Omega)$, $\Lambda_\alpha^{s+2} U(t) \in L^2(\Omega) \times \dot{H}^{-1}(\Omega)$ and therefore $J_{\alpha,h} \Lambda_\alpha^{s+2} U(t) \in S_h^r(\Omega) \times L^2(\Omega)$. Also, $U_h(t) \in S_h^r(\Omega) \times S_h^r(\Omega)$ and $\Lambda_{\alpha,h}^{s+1} U_h(t) \in S_h^r(\Omega) \times S_h^r(\Omega)$.

Thus,

$$\begin{aligned}
 \langle (T_h^* D_t E_h^*(t), D_t E_h^*(t)) \rangle_0 &\geq 0 \\
 \text{and} \quad \frac{1}{2} \frac{d}{dt} \| E_h^*(t) \|_0^2 &\leq \langle (\tilde{\rho}_h(t), D_t E_h^*(t)) \rangle_0.
 \end{aligned}$$

As in the proofs of Propositions 1 and 2, this leads to

$$\sup_{0 < t \leq t^*} \| E_h^*(t) \|_0 \leq C(t^*) \sup_{0 < t \leq t^*} \{ \| \tilde{\rho}_h(t) \|_0 + \| D_t \tilde{\rho}_h(t) \|_0 \},$$

which may be compared with (4.3) of [5].

Now

$$\begin{aligned} D_t \hat{\rho}_h(t) &= (\lambda_{\alpha,h} - J_{\alpha}) \Lambda_{\alpha}^{s+2} U(t) + J_{\alpha,h} \Lambda_{\alpha,h}^{s+3} U(t) - \Lambda_{\alpha}^{s+2} U(t) \\ &\quad + (\Lambda_{\alpha}^{s+1} U(t) - \Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t)), \end{aligned}$$

and these terms are now estimated. We have

$$\begin{aligned} \|(\lambda_{\alpha,h} - J_{\alpha}) \Lambda_{\alpha}^{s+2} U(t)\|_0 &= \|(\lambda_{\alpha} - J) \Lambda_{\alpha}^{s+2} U(t) + {}_{\alpha}(T_h^* - T^*) \Lambda_{\alpha}^{s+2} U(t)\|_0 \\ &\leq ch^{q-1} \|\Lambda_{\alpha}^{s+2} U(t)\|_{q-2} \\ &\quad + \alpha \|[(T_h - T)(\Lambda_{\alpha}^{s+2} U(t))^\top, 0]\|_0 \\ &\leq c(\alpha) h^{q-1} \|U(t)\|_{s+q} \\ &\quad + \|(T_h - T)(\Lambda_{\alpha}^{s+2} U(t))^\top\|_1 \\ &\leq c(\alpha) h^{q-1} \|\Lambda_{\alpha}^{s+2} U(t)\|_{s+q} + h^{q-1} \|\Lambda_{\alpha}^{s+2} U(t)\|_{q-2} \\ &\leq c(\alpha) h^{q-1} \{ \|U_0\|_{s+q} + \|U_h^{s+2} U(t)\|_{q-3} \} \\ &\leq c(\alpha) h^{q-1} \|U_0\|_{s+q}. \end{aligned} \tag{4.6}$$

From (4.4) – (4.5), we obtain

$$\begin{aligned} \|\Lambda_{\alpha}^{s+1} - \Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t)\|_0 &= \|(\lambda_{\alpha} - \Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t))\|_0 \\ &\leq c(\alpha) h^{q-1} \|U_0\|_{s+q}, \end{aligned} \tag{4.7}$$

whereas

$$\begin{aligned} \|\Lambda_{\alpha,h}(\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t) - \Lambda_{\alpha}^{s+2} U(t))\|_0 \\ \leq \|\Lambda_h(\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t) - \Lambda_{\alpha}^{s+2} U(t))\|_0 \\ + \|{}_{\alpha}T_h^*(\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t) - \Lambda_{\alpha}^{s+2} U(t))\|_0. \end{aligned}$$

$$\begin{aligned} &\leq c(\alpha) \|\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t) - \Lambda_{\alpha}^{s+2} U(t)\|_{-1,h}, \\ &\text{since } \|\Lambda_h^* Z\|_0 \leq \|Z\|_{-1,h}. \end{aligned}$$

$$(\text{In fact, } \|\Lambda_h^* Z\|_0^2 = \|\Lambda_h(Z)\|_1^2 \leq \|T_h(Z)\|_1^2 + \|\Lambda_h(Z)\|_0^2)$$

$$\begin{aligned} &= \|J_h^2 Z\|_0^2 = \|Z\|_{-2,h}^2 \\ &\leq \|Z\|_{-1,h}^2. \end{aligned}$$

Therefore,

$$\begin{aligned} \|\Lambda_{\alpha,h}(\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t) - \Lambda_{\alpha}^{s+2} U(t))\|_0 &\leq c(\alpha) \{ \|\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t)\|_{-1} \\ &\quad + h \|\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t)\|_0 \}. \end{aligned}$$

As in the proofs of (4.4) and (4.5),

$$\begin{aligned} \|\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t)\|_{-1} &\leq c(\alpha) h^{q-1} \|U(t)\|_0 \quad \text{and} \\ \|\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t)\|_0 &\leq c(\alpha) h^{q-1} \|U(t)\|_{s+q}. \end{aligned}$$

so that

$$(4.8) \quad \|\Lambda_{\alpha,h}(\Lambda_{\alpha,h} J_{\alpha,h}^{s+2} U(t) - \Lambda_{\alpha}^{s+2} U(t))\|_0 \leq c(\alpha) h^{q-1} \|U_0\|_{s+q}.$$

Then (4.6) – (4.8) yield

$$\|D_t \hat{\rho}_h(t)\|_0 \leq c(\alpha) h^{q-1} \|U_0\|_{s+q}.$$

Similarly,

$$\|\tilde{\rho}_h(t)\|_0 \leq c(\alpha) h^{q-1} \|U_0\|_{s+q}.$$

$$\|\Lambda_h(t)\|_0 \leq c(\alpha) h^{q-1} \|U_0\|_{s+q}.$$

The latter two inequalities lead to the estimate

SUPPLEMENT

$$(4.9) \quad \|E_h^*(t)\|_0 \leq c(t^*, \alpha) h^{q-1} \|U_0\|_{s+q}, \quad 0 \leq t \leq t^*,$$

which together with (4.5), gives

$$\|D_t^s U(t) - D_t^s U_h(t)\|_0 \leq c(t^*, \alpha) h^{q-1} \|U_0\|_{s+q},$$

$$0 \leq t \leq t^*, \quad 2 \leq q \leq r, \quad s \geq 1.$$

To establish negative norm estimates, we need only show that

$$\|D_t^s U(t) - D_t^s U_h(t)\|_{-p,h} \leq c(\alpha, t^*) h^{p+q-1} \|U_0\|_{s+q}, \quad 1 \leq p \leq r-1.$$

Since

$$J_\alpha D_t \Lambda_\alpha^s U(t) + \Lambda_\alpha^s U(t) = 0,$$

we have

$$J_{\alpha,h} D_t \Lambda_\alpha^s U(t) + \Lambda_\alpha^s U(t) = (J_{\alpha,h} - J_\alpha) D_t \Lambda_\alpha^s U(t),$$

and

$$J_h^p J_{\alpha,h} D_t \Lambda_\alpha^s U(t) + J_h^p \Lambda_\alpha^s U(t) = J_h^p (J_{\alpha,h} - J_\alpha) D_t \Lambda_\alpha^s U(t).$$

This can be expressed as

$$J_h^p (J_h + \alpha T_h^*) D_t \Lambda_\alpha^s U(t) + J_h^p \Lambda_\alpha^s U(t) = J_h^p (J_{\alpha,h} - J_\alpha) D_t \Lambda_\alpha^s U(t)$$

or

$$J_h^{p+1} D_t \Lambda_\alpha^s U(t) + J_h^p \Lambda_\alpha^s U(t) = J_h^p (J_{\alpha,h} - J_\alpha - \alpha T_h^*) D_t \Lambda_\alpha^s U(t).$$

On the other hand,

$$J_{\alpha,h} D_t \Lambda_\alpha^s U_h(t) + \Lambda_\alpha^s U_h(t) = 0,$$

so that

$$J_h^p J_{\alpha,h} D_t \Lambda_\alpha^s U_h(t) + J_h^p \Lambda_\alpha^s U_h(t) = 0,$$

which we write as

$$J_h^p (J_h + \alpha T_h^*) D_t \Lambda_\alpha^s U_h(t) + J_h^p \Lambda_\alpha^s U_h(t) = 0$$

or

$$J_h^{p+1} D_t \Lambda_\alpha^s U_h(t) + J_h^p \Lambda_\alpha^s U_h(t) = -\alpha J_h^p T_h^* D_t \Lambda_\alpha^s U_h(t).$$

$$\text{Set } E_h(t) = J_\alpha^s U(t) - \Lambda_\alpha^s U_h(t). \quad \text{Then}$$

$$\begin{aligned} J_h^{p+1} D_t E_h(t) + J_h^p E_h(t) &= J_h^p (J_{\alpha,h} - J_\alpha) D_t \Lambda_\alpha^s U(t) - \alpha J_h^p T_h^* D_t E_h(t) \\ &\equiv J_h^p \delta_h(t) - \alpha J_h^p T_h^* D_t E_h(t). \end{aligned}$$

Take the energy inner product with $J_h^p D_t E_h(t)$:

$$\frac{1}{2} \frac{d}{dt} \|J_h^p E_h(t)\|_0^2 = (\langle J_h^p \delta_h(t), J_h^p D_t E_h(t) \rangle_0 - \alpha \langle J_h^p T_h^* D_t E_h(t), J_h^p D_t E_h(t) \rangle_0).$$

Now

$$\begin{aligned} -\langle (J_h^p T_h^* D_t E_h(t), J_h^p D_t E_h(t))_0 \\ = (-1)^{p+1} \langle (J_h^p T_h^* D_t E_h(t), J_h^p D_t E_h(t))_0 \\ = -\langle (T_h^p T_h^* D_t E_h(t))^I, T_h^p (T_h^* D_t E_h(t))^{II} \rangle_0 \\ = -\langle (T_h^{p+1} (D_t E_h(t))^I, D_t E_h(t))_0 \\ = -\alpha (T_h^{p+1} (D_t E_h(t))^I, D_t E_h(t))_0 \\ \leq \langle (D_t E_h(t))^I, (P_h^1 - P_h^0)(\Lambda_\alpha^{s+1} U(t))^I \rangle_{-p,h} \end{aligned}$$

parallel to the derivation of (2.2), Proposition 2.

$$\text{As in (2.3) of that proposition, we obtain for } 0 \leq t \leq t^*,$$

$$\begin{aligned} \|E_h(t)\|_{-p,h} &\leq c(t^*) \{ \|J_h^p \delta_h(t)\|_{-p,h} + \|D_t \delta_h(t)\|_{-p,h} + \|E_h(0)\|_{-p,h} \\ &\quad + \alpha \|P_h^1 - P_h^0\| (\Lambda_\alpha^{s+1} U(t))_0^I \}_{-p,h} \end{aligned}$$

By (4.6) we have

$$\begin{aligned} \|E_h(0)\|_{-p,h} &= \| (J_s - \Lambda_{\alpha,h}) \Lambda_\alpha^{s+1} U_0 \|_{-p,h} \\ &\leq c(\alpha) h^{p+q-1} \|U_0\|_{s+q-1} \end{aligned}$$

and

$$\begin{aligned} \|\mathcal{D}_t \tilde{\delta}_h(t)\|_{-p,h} &= \|(\mathcal{J}_{\alpha,h} - \mathcal{J}_\alpha)^{s/2} U(t)\|_{-p,h} \\ &\leq c(\alpha) h^{p+q-1} \|U_0\|_{s+q}, \end{aligned}$$

as in (4.6), and also

$$\|\tilde{\delta}_h(t)\|_{-p,h} \leq c(\alpha) h^{p+q-1} \|U_0\|_{s+q-1}.$$

By the analysis of (2.4), Proposition 2, and using (4.3),

$$\begin{aligned} \|(P_h^1 - P_h^0)(\Lambda_\alpha^{s+1} U(t))^\dagger\|_{-p,h} &\leq c h^{p+q-1} \|(\Lambda_\alpha^{s+1} U(t))^\dagger\|_{q-1} \\ &\leq c h^{p+q-1} \|\Lambda_\alpha^{s+1} U(t)\|_{q-2} \\ &\leq c(\alpha) h^{p+q-1} \|U(t)\|_{s+q-1} \\ &\leq c(\alpha) h^{p+q-1} \|U_0\|_{s+q-1}. \end{aligned}$$

We have thus obtained

$$\begin{aligned} \|E_h(t)\|_{-p,h} &\leq c(t^*, \alpha) h^{p+q-1} \|U_0\|_{s+q} \quad \text{for } 0 \leq t \leq t^*, \quad 1 \leq p \leq r-1 \\ \text{or} \quad \|\mathcal{D}_t^s U(t) - D_t^s U_h(t)\|_{-p,h} &\leq c(t^*, \alpha) h^{p+q-1} \|U_0\|_{s+q}. \end{aligned}$$