

# Supplement to Boundary Value Techniques for Initial Value Problems in Ordinary Differential Equations

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## APPENDIX

In [1], the following Theorem 6 was presented for the error of a Galerkin method for initial value problems. Here we present a proof.

**THEOREM.** *Let  $U$  be the solution of (3.2) where (3.3), (3.4) in [1] are satisfied. Then the Galerkin solution  $\tilde{U}$ , in the space of piecewise polynomial continuous functions of degree  $p$ , defined by (3.5a,b,c) in [1] satisfies*

$$\|U - \tilde{U}\| = O(h^{p+\nu}) (\|eU\|_{p+2}^2 + \|U\|_{p+1}^2)^{\frac{1}{2}}, \quad h \rightarrow 0,$$

where  $\nu = 1$  if  $p = 1$ ,  $1 \geq \nu \geq \frac{1}{2}$  if  $p = 3, 5, \dots$  and  $\nu = 0$  if  $p$  is even, and

$$\|V\|^2 = \frac{1}{2}(eV(T), V(T)) - \int_{t_0}^T \rho(t) |V(t)|^2 dt.$$

**PROOF.** Our first objective is to derive an estimate of  $\theta$ . We have  $\theta(t_0) = \eta(t_0) = 0$  and

$$(1) \quad a(\tilde{U}; \theta) - a(U_I; \theta) = \int_{t_0}^T \{(\epsilon \dot{\theta}, \theta) - (F(t, \tilde{U}) - F(t, U_I), \theta)\} dt.$$

From

$$\int_{t_0}^T (\epsilon \dot{\theta}, \theta) dt = - \int_{t_0}^T (\dot{\theta}, \epsilon \theta) dt + [(\epsilon \theta, \theta)]_{t_0}^T,$$

it follows that

$$\int_{t_0}^T (\epsilon \dot{\theta}, \theta) dt = \frac{1}{2}(\epsilon \theta(T), \theta(T)).$$

Hence by (3.3),

$$(5) \quad \int_{t_0}^T |\dot{\eta}_k \theta_k dt| \leq \rho_0 \int_{t_0}^T \theta_k^2 dt + \frac{1}{2} \eta_k^2(T) + O(h^2(p+\nu_k)) \|U_k\|_{p+2}^2 \begin{cases} \nu_k=1, & p=1 \\ \nu_k \geq 1, & p=3,5,\dots \end{cases}$$

i.e.,

$$\int_{t_0}^T (\epsilon \dot{\eta}_k \theta_k) dt \leq \rho_0 \int_{t_0}^T \|\theta(t)\|^2 dt + \frac{1}{2} (\epsilon \theta(T), \theta(T)) + O(h^2(p+\nu_k)) \|U_k\|_{p+2}^2$$

We have

$$(6) \quad \int_{t_0}^T \dot{\eta}_k \theta_k dt = \int_{t_0}^T \dot{\eta}_k \theta_k dt + \int_{t_0}^T \dot{\eta}_k \theta_k dt.$$

From (4) there follows

$$\int_{t_0}^T |\dot{\eta}_k \theta_k dt| \leq O(h^{p+1}) \left\{ \int_{t_0}^T \theta_k^2 dt \right\}^{\frac{1}{2}} \|U_k\|_{p+2}^2 + O(h^2(p+1)) \|U_k\|_{p+2}^2,$$

and it remains to consider the first term in (6). We have

$$\int_{t_0}^T \dot{\eta}_k \theta_k dt = - \int_{t_0}^T \dot{\eta}_k \theta_k dt.$$

As test functions  $\tilde{\theta}_{i,j}$  we choose the basis functions of degree  $q$ ,  $q = 1, 2, \dots, p$ , at each  $t_i$ ,  $i = 1, 2, \dots, N$ , with support on  $(t_{i-1}, t_{i+1})$ , see Fig. 1.

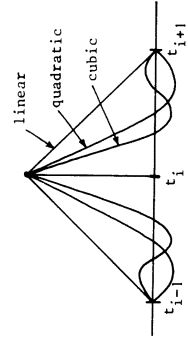


Figure 1 Test functions  $\tilde{\theta}_{i,j}$ ,  $j = 1, 2, \dots, p$  ( $p=3$ ).

$$(2) \quad a(\tilde{U}; \theta) - a(U_I; \theta) = \frac{1}{2} (\epsilon \theta(T), \theta(T)) - \int_{t_0}^T (F(t, \tilde{U}) - F(t, U_I), \theta) dt$$

$$\geq \frac{1}{2} (\epsilon \theta(T), \theta(T)) - \int_{t_0}^T \rho(t) \|\theta(t)\|^2 dt := \|\theta\|^2.$$

Further we get from (3.6) and the Lipschitz continuity (3.4), in [1]

$$(3) \quad a(\tilde{U}; \theta) - a(U_I; \theta) = a(\tilde{U}; \theta) - a(U; \theta) + a(U; \theta) - a(U_I; \theta) =$$

$$= a(U; \theta) - a(U_I; \theta) \leq \int_{t_0}^T (\epsilon \dot{\eta}_k \theta_k) dt + c \int_{t_0}^T \|\eta\| \|\theta\| dt.$$

First we shall estimate the term  $\int_{t_0}^T (\epsilon \dot{\eta}_k \theta_k) dt$ . Since  $\epsilon$  is a diagonal matrix, we may consider each component individually, i.e.,  $\int_{t_0}^T \dot{\eta}_k \theta_k dt$ , where  $\eta_k, \theta_k$  are scalar functions. Since  $\theta_k \in S_h$ , we have

$$\theta_k = \sum_{i=0}^{N-1} \sum_{j=1}^p \nu_{i,j} \tilde{\theta}_{i,j}$$

where  $\{\tilde{\theta}_{i,j}\}$ ,  $i = 0, 1, \dots, N-1$ ,  $j = 1, 2, \dots, p$  is a set of basis functions (test functions) spanning  $S_h$ , but not necessarily equal to  $\theta_{i,j}$ . We write  $\eta_k = \tilde{\eta}_k + \eta_k$ , where  $\tilde{\eta}_k$  is the leading (polynomial) term in an expansion of the interpolation error (for more details, see e.g. Axelsson and Gustafsson [2]). For instance, if we use piecewise linear basis functions, then at  $t_i$ ,  $i = 1, 3, \dots, N-1$  we have

$$\tilde{\eta}_k(t) = \begin{cases} \tilde{u}_k(t_i)(t-t_{i-1})(t-t_i), & t_{i-1} \leq t \leq t_i \\ \tilde{u}_k(t_i)(t-t_i)(t-t_{i+1}), & t_i < t \leq t_{i+1} \end{cases}$$

(For simplicity, we may assume that  $N$  is even.) With the piecewise polynomial basis functions of degree  $p$ , an easy calculation shows that

$$(4) \quad \left\{ \int_{t_0}^T \tilde{\eta}_k^2 dt \right\} = O(h^p) \|U_k\|_{p+1}^2, \left\{ \int_{t_0}^T \eta_k^2 dt \right\} = O(h^{p+1}) \|U_k\|_{p+2}^2, \quad h \rightarrow 0.$$

We shall prove that because of cancellation

We have

$$(7) \quad \int_{t_0}^T \tilde{\eta}_k \dot{\phi}_k dt = \sum_{i,j} \int_{t_{i,j}}^T \gamma_{i,j} \tilde{\eta}_k \dot{\phi}_{i,j} dt = \sum_{i=1}^{N-1} \sum_{j=1}^p \gamma_{i-1,j} \int_{t_{i-1}}^{t_{i+1}} \tilde{\eta}_k \dot{\phi}_{i-1,j} dt + \sum_{j=1}^p \gamma_{N-1,j} \int_{t_{N-1}}^{t_N} \tilde{\eta}_k \dot{\phi}_{N-1,j} dt.$$

Note that  $\tilde{\eta}_k$  and  $\dot{\phi}_k$  are polynomials of degree  $p+1$  and  $p-1$ , respectively, on each subinterval. Also note that  $\tilde{\eta}_k$  is zero at the  $(p+1)$  Lobatto points. Hence, if we apply Lobatto quadrature we get (from the error term of the quadrature),

$$\begin{aligned} \int_{t_{i-1}}^{t_i} \tilde{\eta}_k \dot{\phi}_{i-1,j} dt &= O(h^{2p+1}) \frac{\partial^{2p}}{\partial t^{2p}} (\tilde{\eta}_k \dot{\phi}_{i-1,j}) \\ &= O(h^{2p+1}) \binom{2p}{p+1} \frac{\partial^{p+1}}{\partial t^{p+1}} (\tilde{\eta}_k) \frac{\partial^p}{\partial t^p} (\dot{\phi}_{i-1,j}) = O(h^{p+1}). \end{aligned}$$

The loss of  $p$  in the exponent is due to the fact that

$$\frac{\partial^p}{\partial t^p} (\tilde{\eta}_k \dot{\phi}_{i-1,j}) = O(h^{-p}).$$

Note however that for  $p$  odd this derivative, which is piecewise constant, appears with the same numerical value but with opposite signs in the two adjacent intervals  $(t_{i-1}, t_i)$  and  $(t_i, t_{i+1})$ . Hence

$$\int_{t_{i-1}}^{t_{i+1}} \tilde{\eta}_k \dot{\phi}_{i-1,j} dt = 0, \quad i = 1, 2, \dots, N-1,$$

and by (7)

$$(8) \quad \int_{t_0}^T \tilde{\eta}_k \dot{\phi}_k dt = \sum_{j=1}^p \gamma_{N-1,j} \int_{t_{N-1}}^{t_N} \tilde{\eta}_k \dot{\phi}_{N-1,j} dt.$$

Consider first the case of piecewise linear basis functions ( $p=1$ ). Then we only have one test function at  $t_N$ . With  $\tilde{\eta}_k \dot{\phi}_{N-1,1} = \dot{\phi}_k$ ,  $\gamma_{N-1,1} = \gamma_N = \theta_k(T)$ , we get

$$\begin{aligned} \left| \int_{t_0}^T \tilde{\eta}_k \dot{\phi}_k dt \right| &= |\gamma_N \int_{t_{N-1}}^{t_N} \tilde{\eta}_k \dot{\phi}_k dt| \leq |\theta_k(T)| \max_{t_{N-1} \leq t \leq t_N} |\tilde{\eta}_k(t)| \\ &= |\theta_k(T)| |O(h^{p+1})| \|u_k\|_{p+2}. \end{aligned}$$

Here we have used the Sobolev inequality,

$$\max_{t_0 \leq t \leq T} |u_k^{(p+1)}| \leq C \|u_k\|_{p+1}, \quad u_k \in H^{p+2}(t_0, T).$$

Hence (5) follows for  $p=1$ . For the general case,  $p > 1$ , we choose  $\dot{\phi}_{N-1,j} = \phi_{N-1,j}$  and we then get

$$(9) \quad \begin{aligned} \left| \int_{t_0}^T \tilde{\eta}_k \dot{\phi}_k dt \right| &= \left| \sum_{j=1}^p \gamma_{N-1,j} \int_{t_{N-1}}^{t_N} \tilde{\eta}_k \dot{\phi}_{N-1,j} dt \right| \\ &\leq C \sum_{j=1}^p |\gamma_{N-1,j}| \max_{t_{N-1} \leq t \leq T} |\tilde{\eta}_k| \leq C \left\{ h^{-1} \int_{t_{N-1}}^{t_N} \theta_k^2 dt \right\}^{\frac{1}{2}} \max_{t_0 \leq t \leq T} |\tilde{\eta}_k|. \end{aligned}$$

Here we have used the fact that

$$\sum_{j=1}^p |\gamma_{N-1,j}| \text{ and } \left\{ h^{-1} \int_{t_{N-1}}^{t_N} \theta_k^2 dt \right\}^{\frac{1}{2}}$$

are both norms in a finite dimensional space ( $\mathbb{R}^p$ ), and hence equivalent (uniformly in  $h$ ). Finally we get from (9),

$$\left| \int_{t_0}^T \tilde{\eta}_k \dot{\phi}_k dt \right| = C \left\{ \int_{t_0}^T \theta_k^2 dt \right\}^{\frac{1}{2}} \|\theta_k\|_{k,p+1}$$

where

$$(10) \quad v_k = \min \left\{ \frac{1}{2}, 1 + \left[ \log \left( \int_{t_0}^T \theta_k^2 dt / \int_{t_0}^{t_N} \theta_k^2 dt \right) / \log h \right] \right\}.$$

Together with (3.14) and (3.15) this implies (3.12a) for  $p = 3, 5, \dots$ , where

$$(11) \quad 1 \geq v = \min_{1 \leq k \leq m} v_k \geq \frac{1}{2}.$$

Finally, from (2), (3) and (5) we get

$$\begin{aligned} \|\theta\|^2 &\leq O(h^{2(p+\nu)})\|\epsilon\|_{p+2}^2 + \|\eta\|^2 \\ &\leq O(h^{2(p+\nu)})\left\{\|\epsilon\|_{p+2}^2 + \|\eta\|_{p+1}^2\right\}^{\frac{1}{2}}, \quad p = 1, 3, \dots \end{aligned}$$

Clearly, this estimate with  $\nu = 0$  is also valid for  $p$  even. We now obtain the Galerkin error

$$\begin{aligned} \|\tilde{U} - \tilde{U}_I\| &\leq \|U - U_I\| + \|\tilde{U} - \tilde{U}_I\| = \|\eta\| + \|\theta\| \leq \\ &O(h^{p+\nu})\left\{\|\epsilon\|_{p+2}^2 + \|\eta\|_{p+1}^2\right\}^{\frac{1}{2}}, \quad h \rightarrow 0. \quad \square \end{aligned}$$

Note that if  $U$  is smooth,  $\tilde{U}$  and  $U_I$  will be smooth, so

$$\int_{t_0}^T \int_K \frac{d^2}{dt} / \int_{t_{N-1}}^T \frac{d^2}{dt} = O(h^{-1}).$$

Hence it follows from (10), (11) that  $v$  will be close to 1.

REFERENCES

[1] AXELSSON, A.O.H. and J.G. VERWER, *Boundary value techniques for initial value problems in ordinary differential equations*, this issue.  
 [2] AXELSSON, A.O.H. and I. GUSTAFSSON, *Quasi optimal finite element approximation of first order hyperbolic and of convection-dominated convection diffusion equations*, in: *Analytical and numerical approaches to asymptotics in analysis*, eds. O. Axelsson, L.S. Frank and A. van der Sluis, North-Holland Mathematics Studies 47, North-Holland Publishing Company, Amsterdam - New York - Oxford, 1981.