

Supplement to
ADAPTIVE STREAMLINE DIFFUSION FINITE ELEMENT METHODS
FOR STATIONARY CONVECTION-DIFFUSION PROBLEMS

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Proof of Lemma 3.3. We find that $\rho = u - \hat{u}$ solves the following problem:

$$\begin{aligned} \rho_x - \operatorname{div}(\varepsilon \nabla \rho) &= \phi && \text{in } \Omega, \\ \rho &= 0 && \text{on } \Gamma_- \cup \Gamma_0, \\ \frac{\partial \rho}{\partial n} &= 0 && \text{on } \Gamma_+, \end{aligned}$$

where $\phi = -\operatorname{div}((\hat{\varepsilon} - \varepsilon)\nabla \hat{u})$.

From Lemma 1.1 and the fact that $\|\rho\| \leq C\|\rho_x\|$ we get that

$$(A) \quad \|\rho\| \leq C\|\operatorname{div}((\hat{\varepsilon} - \varepsilon)\nabla \hat{u})\|.$$

Since ε is constant, we have that

$$\begin{aligned} (B) \quad \operatorname{div}((\hat{\varepsilon} - \varepsilon)\nabla \hat{u}) &= \nabla \hat{\varepsilon} \cdot \nabla \hat{u} + (\hat{\varepsilon} - \varepsilon)\Delta \hat{u} \\ &= \nabla \hat{\varepsilon} \cdot \nabla \hat{u} + \hat{\varepsilon}^{-1}(\hat{\varepsilon} - \varepsilon)(\hat{u}_x - f - \nabla \hat{\varepsilon} \cdot \nabla \hat{u}) \\ &= \hat{\varepsilon}^{-1}\varepsilon \nabla \hat{\varepsilon} \cdot \nabla \hat{u} + \hat{\varepsilon}^{-1}(\hat{\varepsilon} - \varepsilon)(\hat{u}_x - f). \end{aligned}$$

Further, with $\varphi = \hat{\varepsilon}^{-2}(\hat{\varepsilon} - \varepsilon)^2$ we have that

$$\begin{aligned} \|\hat{u}_x - f\|_{\varphi}^2 &= (\varphi(\hat{u}_x - f), \operatorname{div}(\hat{\varepsilon}\nabla \hat{u})) \\ &= \int_{\Gamma} \varphi(\hat{u}_x - f)\hat{\varepsilon} \frac{\partial \hat{u}}{\partial n} d\Gamma - (\nabla \varphi(\hat{u}_x - f), \hat{\varepsilon}\nabla \hat{u}) \\ &\quad - (\varphi \nabla \hat{u}_x, \hat{\varepsilon}\nabla \hat{u}) + (\varphi \nabla f, \hat{\varepsilon}\nabla \hat{u}) \\ &= I + II + III + IV. \end{aligned}$$

Here

$$III = -\frac{1}{2} \int_{\Gamma} \varphi \hat{\varepsilon} |\nabla \hat{u}|^2 n_1 d\Gamma + \frac{1}{2} ((\varphi \hat{\varepsilon})_x \nabla \hat{u}, \nabla \hat{u}) = V + VI,$$

and since f vanishes on Γ , $\partial \hat{u} / \partial n$ on Γ_+ and \hat{u} on Γ_- , we get as in (1.8)

$$\begin{aligned} I + V &= \int_{\Gamma} \varphi \hat{\varepsilon} (\hat{u}_x \frac{\partial \hat{u}}{\partial n} - \frac{1}{2} |\nabla \hat{u}|^2 n_1) d\Gamma \\ &= -\frac{1}{2} \int_{\Gamma} \varphi \hat{\varepsilon} |\nabla \hat{u}|^2 |n_1| d\Gamma \leq 0. \end{aligned}$$

Using obvious estimates for the terms II and IV , and the fact that $\varphi^{-1/2}\nabla\varphi = 2\varepsilon\hat{\varepsilon}^{-2}\nabla\hat{\varepsilon}$, we obtain

$$\begin{aligned} \|\hat{u}_x - f\|_{\varphi}^2 &\leq \frac{1}{2}\|\hat{u}_x - f\|_{\varphi}^2 + 2\|\varepsilon\hat{\varepsilon}^{-1}\nabla\hat{\varepsilon} \cdot \nabla\hat{u}\|_{\varphi}^2 \\ &\quad + \frac{1}{2}\|\varphi\hat{\varepsilon}^{1/2}\nabla f\|_{\varphi}^2 + \frac{1}{2}\|\hat{\varepsilon}^{1/2}\nabla\hat{u}\|_{\varphi}^2 + \frac{1}{2}\langle(\varphi\hat{\varepsilon})_x\nabla\hat{u}, \nabla\hat{u}\rangle. \end{aligned}$$

From the identity (B) we may thus conclude, with σ as above, that

$$\begin{aligned} \|\operatorname{div}((\hat{\varepsilon} - \varepsilon)\nabla\hat{u})\|_{\varphi}^2 &\leq 2(\|\hat{\varepsilon}^{-1}\varepsilon\nabla\hat{\varepsilon} \cdot \nabla\hat{u}\|_{\varphi}^2 + \|\hat{u}_x - f\|_{\varphi}^2) \\ &\leq 2(\|\sigma\nabla\hat{u}\|_{\varphi}^2 + \|\varphi\nabla f\|_{\varphi}^2). \end{aligned}$$

Together with (A) this proves the desired error bound for ρ and completes the proof of Lemma 3.3. \square

Proof of Lemma 3.4. We have that

$$(\theta_x \cdot v + \delta v_x) + (\varepsilon\nabla\theta, \nabla v) - (\operatorname{div}(\varepsilon\nabla\theta), \delta v_x)_T = 0, \quad \forall v \in V.$$

Now let z be the solution of

$$(C) \quad \begin{aligned} -z_x - \operatorname{div}(\varepsilon\nabla z) &= -\operatorname{div}(\varepsilon\nabla\theta) && \text{in } \Omega, \\ z &= 0 && \text{on } \Gamma_- \cup \Gamma_0, \\ \varepsilon\frac{\partial z}{\partial n} + n_1 z &= \varepsilon\frac{\partial\theta}{\partial n} && \text{on } \Gamma_+. \end{aligned}$$

We find that

$$\begin{aligned} \|\nabla\theta\|_{\varepsilon}^2 &= (\theta, -z_x - \operatorname{div}(\varepsilon\nabla z)) + \int_{\Gamma_+} \varepsilon\theta\frac{\partial\theta}{\partial n}d\Gamma = (\theta_{x,z}) + (\varepsilon\nabla\theta, \nabla z) \\ &= (\theta_{x,z}, z - \hat{z} - \delta\hat{z}_x) + (\varepsilon\nabla\theta, \nabla(z - \hat{z})) + (\operatorname{div}(\varepsilon\nabla\theta), \delta\hat{z}_x)_T \\ &= (f - U_x + \nabla\hat{\varepsilon} \cdot \nabla U, z - \hat{z} - \delta\hat{z}_x) + \sum_{\Gamma} \int_{\Gamma} \varepsilon\left|\frac{\partial U}{\partial n_{\tau}}\right|(z - \hat{z})d\Gamma \\ &= I + II. \end{aligned}$$

With $r = |f - U_x + \nabla\hat{\varepsilon} \cdot \nabla U|$, we have that

$$|I| \leq (r, |z - \hat{z}| + \delta|\hat{z}_x|) \leq C\|\min_{\star}(1, h\hat{\varepsilon}^{-1/2})_T\|(\|z\| + \|\nabla z\|_{\varepsilon}).$$

Similarly

$$|II| \leq C\|\min_{\star}(1, h\hat{\varepsilon}^{-1/2})_{\varepsilon}D_k^2U\|(\|z\| + \|\nabla z\|_{\varepsilon}).$$

Multiplying the equation in (C) by z and integrating over Ω we obtain, using the given boundary conditions,

$$\frac{1}{2} \int_{\Gamma_+} z^2 n_1 + \|\nabla z\|_{\varepsilon}^2 = (\varepsilon\nabla z, \nabla\theta) \leq \|\nabla z\|_{\varepsilon}\|\nabla\theta\|_{\varepsilon},$$

from which follows at once that $\|\nabla z\|_{\varepsilon} \leq \|\nabla\theta\|_{\varepsilon}$. If we repeat the arguments in the first part of the proof of Lemma 1.2 we easily derive the same control for z , or $\|z\| \leq C\|\nabla\theta\|_{\varepsilon}$. Together our estimates now show that

$$\|\nabla\theta\|_{\varepsilon} \leq C(\|\min_{\star}(1, h\hat{\varepsilon}^{-1/2})_T\| + \|\min_{\star}(1, h\hat{\varepsilon}^{-1/2})_{\varepsilon}D_k^2U\|).$$

Clearly, by estimating the terms I and II together, we can derive the more precise estimate (3.9). This completes the proof of Lemma 3.4. \square