

**Supplement to**  
**A NUMERICAL LIAPUNOV-SCHMIDT METHOD WITH**  
**APPLICATIONS TO HOPF BIFURCATION ON A SQUARE**

PETER ASHWIN, KLAUS BÖHMER, AND MEI ZHEN

4. COMPUTATION OF THE LIAPUNOV-SCHMIDT REDUCTION

We provide here the details of the computations performed to provide the reduced bifurcation equations for Brusselator Hopf bifurcation. We use splittings and null space projections as defined in § 3. For  $\lambda, \tau$  in (37)-(39) and for any

$$(53) \quad \eta := (z, \lambda, \tau) = \left( \sum_{i=1}^4 \alpha_i \psi_i, \lambda, \tau \right) \in \text{Ker}(\partial_u \Phi_0) \times \mathbb{R}^2 = \text{Ker}(\Phi'_0),$$

we find that the truncated bifurcation equations to second order are given by

$$(54) \quad \begin{aligned} B_2(z, \lambda, \tau) &= (I - \hat{Q}) j_2 R \left( \sum_{i=1}^4 \alpha_i \psi_i, \lambda, \tau \right) \\ &= (I - \hat{Q}) \left\{ \left( \begin{array}{cc} 1 & 0 \\ -1 & 0 \end{array} \right) \lambda \sum_{i=1}^4 \alpha_i \psi_i + \left( \begin{array}{c} 1 \\ -1 \end{array} \right) \left[ \frac{B_0}{A_0} \left( \sum_{i=1}^4 \alpha_i \psi_i^1 \right)^2 \right. \right. \\ &\quad \left. \left. + 2A_0 \left( \sum_{i=1}^4 \alpha_i \psi_i^1 \right) \left( \sum_{i=1}^4 \alpha_i \psi_i^2 \right) \right] - \tau \partial_t \sum_{i=1}^4 \alpha_i \psi_i \right\}, \end{aligned}$$

where we have used the notation  $\psi_i = (\psi_i^1, \psi_i^2)^T$  and  $j_2$  truncates to the polynomial of degree 2 in the Taylor expansion of  $\Phi$  at  $(0, 0, 0)$  with respect to  $\alpha_i, \lambda$  and  $\tau$ . In view of the orthogonality properties of  $\{\phi_{ki}\}$ , we can write

$$\begin{aligned} B_2(z, \lambda, \tau) &= (I - \hat{Q}) \left[ \left( \begin{array}{cc} 1 & 0 \\ -1 & 0 \end{array} \right) \lambda \sum_{i=1}^4 \alpha_i \psi_i - \tau \partial_t \sum_{i=1}^4 \alpha_i \psi_i \right] \\ &= \sum_{j=1}^4 \left\langle \psi_j^*, \left( \begin{array}{c} 1 \\ -1 \end{array} \right) \lambda \sum_{i=1}^4 \alpha_i \psi_i^1 - \tau \partial_t \left( \sum_{i=1}^4 \alpha_i \psi_i \right) \right\rangle \psi_j \\ &= \frac{1}{2} \{ [(\alpha_1 - \alpha_2(P_{11} - P_{12}))\lambda - 2\tau\alpha_2] \psi_1 + [(P_{11} - P_{12})\alpha_1 + \alpha_2]\lambda + 2\tau\alpha_1 \} \psi_2 \\ &\quad + [(\alpha_3 - \alpha_4(P_{11} - P_{12}))\lambda - 2\tau\alpha_4] \psi_3 + [(P_{11} - P_{12})\alpha_3 + \alpha_4]\lambda + 2\tau\alpha_3 \} \psi_4 \\ &= 0, \end{aligned}$$

which gives

$$(55) \quad \frac{1}{2} \begin{pmatrix} \lambda & \lambda \\ P_{11} - P_{12} & \lambda + 2\tau \end{pmatrix} - \begin{pmatrix} P_{11} - P_{12} & \lambda - 2\tau \\ \lambda & \alpha_3 \alpha_4 \end{pmatrix} \begin{pmatrix} \alpha_1 & \alpha_3 \\ \alpha_2 & \alpha_4 \end{pmatrix} = 0.$$

Evidently,  $B_2(x, \lambda, \tau)$  is not determined as it has vertically branching bifurcating solutions; we have a linear equation for  $\{\alpha_i\}$  that has only zero as a solution unless  $\lambda, \tau$  are both zero. To investigate the structure of solution branches of (37) at  $(0, 0, 0)$ , the next step of the truncated Liapunov-Schmidt method is needed.

**4.1. Calculating  $w_2$ .** To find the third-order truncation, we first need to solve  $w_2$  from the equation

$$\begin{aligned} \partial_x \Phi(0, 0, 0)w_2 &= -\hat{Q}_{12}R \left( \sum_{i=1}^4 \alpha_i \psi_i, \lambda, \tau \right) \\ &= -\hat{Q} \left\{ \begin{pmatrix} 1 & 0 \\ -1 & 0 \end{pmatrix} \lambda \sum_{i=1}^4 \alpha_i \psi_i + \begin{pmatrix} 1 \\ -1 \end{pmatrix} \left[ \frac{B_0}{A_0} \left( \sum_{i=1}^4 \alpha_i \psi_i \right)^2 \right. \right. \\ &\quad \left. \left. + 2A_0 \left( \sum_{i=1}^4 \alpha_i \psi_i \right) \left( \sum_{i=1}^4 \alpha_i \psi_i^2 \right) \right] - \tau \theta_i \sum_{i=1}^4 \alpha_i \psi_i \right\} \\ &=: f(\alpha, \lambda, \tau). \end{aligned}$$

Note that the right-hand side is a periodic function in  $t$ . More precisely, we have

$$(56) \quad f(\alpha, \lambda, \tau) = f_0 + f_1 \cos t + f_2 \sin t + f_3 \cos 2t + f_4 \sin 2t,$$

where  $f_i, i = 0, 1, \dots, 4$ , are functions of  $\alpha, \lambda, \tau$  and  $x, y$  only. Decomposing the expected solution in the form

$$(57) \quad w_2 = w_0^2 + w_2^0 \cos t + w_2^1 \sin t + w_2^2 \cos 2t + w_2^3 \sin 2t,$$

we solve the coefficients from the equations

$$(58a) \quad L(B_0)w_0^0 = f_0(\alpha, \lambda, \tau),$$

$$(58b) \quad \begin{pmatrix} L(B_0) & -w_0 I \\ w_0 I & L(B_0) \end{pmatrix} \begin{pmatrix} w_2^1 \\ w_2^2 \end{pmatrix} = \begin{pmatrix} f_1(\alpha, \lambda, \tau) \\ f_2(\alpha, \lambda, \tau) \end{pmatrix},$$

$$(58c) \quad \begin{pmatrix} L(B_0) & -2w_0 I \\ 2w_0 I & L(B_0) \end{pmatrix} \begin{pmatrix} w_2^3 \\ w_2^4 \end{pmatrix} = \begin{pmatrix} f_3(\alpha, \lambda, \tau) \\ f_4(\alpha, \lambda, \tau) \end{pmatrix}.$$

Determining the expressions  $f_0, \dots, f_4$  in terms of the parameters of the problem and the null space coordinates, and then selecting the coefficients of the various monomials in the  $\alpha_i$  gives us a set of linear problems on the square. To obtain

these, we study the right-hand sides of the equations (58):

$$(59) \quad f_0(\alpha, \lambda, \tau) = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \sum_{i,j=1}^4 \alpha_i \alpha_j \left[ \frac{B_0}{2A_0} (\mu_i \nu_j + \xi_i \xi_j) + A_0 (\mu_i \nu_j + \xi_i \eta_j) \right],$$

$$(60) \quad f_1(\alpha, \lambda, \tau) = -\hat{Q} \sum_{i=1}^4 \alpha_i \begin{bmatrix} 1 \\ -1 \end{bmatrix} \mu_i \lambda - \tau \begin{pmatrix} \xi_i \\ \eta_i \end{pmatrix},$$

$$(61) \quad f_2(\alpha, \lambda, \tau) = -\hat{Q} \sum_{i=1}^4 \alpha_i \begin{bmatrix} 1 \\ -1 \end{bmatrix} \xi_i \lambda + \tau \begin{pmatrix} \mu_i \\ \nu_i \end{pmatrix},$$

$$(62) \quad f_3(\alpha, \lambda, \tau) = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \sum_{i,j=1}^4 \alpha_i \alpha_j \left[ -\frac{B_0}{2A_0} (\mu_i \nu_j - \xi_i \xi_j) + A_0 (\mu_i \nu_j - \xi_i \eta_j) \right],$$

$$(63) \quad f_4(\alpha, \lambda, \tau) = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \sum_{i,j=1}^4 \alpha_i \alpha_j \left[ \frac{B_0}{A_0} \mu_i \xi_j + A_0 (\mu_i \eta_j + \xi_i \nu_j) \right],$$

where we have used the notation

$$\psi_i = \begin{pmatrix} \mu_i \\ \nu_i \end{pmatrix} \cos t + \begin{pmatrix} \xi_i \\ \eta_i \end{pmatrix} \sin t, \quad i = 1, \dots, 4.$$

For the given basis of  $\text{Ker}(\partial_x \Phi_0)$  in (43), elementary calculations yield

$$(64) \quad f_0(\alpha, \lambda, \tau) = -\begin{pmatrix} 1 \\ -1 \end{pmatrix} \left[ \frac{B_0}{2A_0} (1 + P_{11}^2) + A_0 P_{11} P_{21} \right] (\alpha_1^2 \phi_{k1}^2 + 2\alpha_1 \alpha_3 \phi_{k1} \phi_{k2}) + \dots,$$

while the coefficients of the terms  $\alpha_1 \alpha_2, \alpha_1 \alpha_4$  are equal to zero. Similarly,

$$(65) \quad \begin{pmatrix} f_1(\alpha, \lambda, \tau) \\ f_2(\alpha, \lambda, \tau) \end{pmatrix} = -\hat{Q} \begin{pmatrix} \lambda - \tau P_{11} & -\lambda P_{11} - \tau \\ -\lambda - \tau P_{11} & \lambda P_{11} \\ \lambda P_{11} + \tau & \lambda - \tau P_{11} \\ -\lambda P_{11} & -\lambda - \tau P_{21} \end{pmatrix} \begin{pmatrix} \alpha_1 \phi_{k1} + \alpha_3 \phi_{k2} \\ \alpha_2 \phi_{k1} + \alpha_4 \phi_{k2} \end{pmatrix}$$

and

$$(66) \quad \begin{aligned} f_3(\alpha, \lambda, \tau) &= -\begin{pmatrix} 1 \\ -1 \end{pmatrix} \left\{ \frac{B_0}{2A_0} (1 - P_{11}^2) - A_0 P_{11} P_{21} \right\} (\alpha_1^2 \phi_{k1}^2 + 2\alpha_1 \alpha_3 \phi_{k1} \phi_{k2}) \\ &\quad - 2 \left( \frac{B_0}{A_0} P_{11} + A_0 P_{21} \right) (\alpha_1 \alpha_2 \phi_{k1}^2 + \alpha_1 \alpha_4 \phi_{k1} \phi_{k2}) + \dots, \\ f_4(\alpha, \lambda, \tau) &= -\begin{pmatrix} 1 \\ -1 \end{pmatrix} \left\{ \frac{B_0}{A_0} P_{11} + A_0 P_{21} \right\} (\alpha_1^2 \phi_{k1}^2 + \alpha_1 \alpha_3 \phi_{k1} \phi_{k2}) \\ &\quad + \frac{B_0}{A_0} (1 - P_{11}^2) - 2A_0 P_{21} P_{11} (\alpha_1 \alpha_2 \phi_{k1}^2 + \alpha_1 \alpha_4 \phi_{k1} \phi_{k2}) + \dots. \end{aligned}$$

Since  $f_i$  are polynomials of  $\alpha \in \mathbb{R}^4$  and  $\lambda, \tau \in \mathbb{R}$ , in particular,  $f_0, f_3, f_4$  are independent of  $\lambda, \tau$ , the functions  $w_2^i, i = 0, \dots, 4$ , are also polynomials of  $\alpha, \lambda, \tau$

of the same form as  $f_i$ . Their coefficients can be solved from the corresponding equations. For example, the equation for the coefficient independent of  $t$  will be

$$(67) \quad L(B_0)w_0^{0ij} = - \begin{pmatrix} 1 \\ -1 \end{pmatrix} \left[ \frac{B_0}{2A_0}(\mu_i\mu_j + \xi_i\eta_j) + A_0(\mu_i\nu_j + \xi_i\eta_j) \right]$$

for  $i, j = 1, \dots, 4$ , and one gets the solution  $w_0^0$  of (58) as

$$w_0^0 = \sum_{i,j=1}^4 \alpha_i \alpha_j w_0^{0ij}.$$

In fact, (58b) can be solved analytically in the following way. The restriction of the operator

$$\begin{pmatrix} L(B_0) & -\omega_0 I \\ \omega_0 I & L(B_0) \end{pmatrix}$$

to the subspace  $\text{span}\left\{ \begin{pmatrix} \phi_{4i} \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ \phi_{4i} \end{pmatrix}, \begin{pmatrix} \phi_{4i} \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ \phi_{4i} \end{pmatrix} \right\}$  reduces to the matrix

$$\omega_0 \begin{pmatrix} P & -I \\ I & P \end{pmatrix}.$$

Its inverse can be given explicitly (cf. (1)):

$$\omega_0 \hat{Q} \begin{pmatrix} P & -I \\ I & P \end{pmatrix}^{-1} \hat{Q} = -\frac{1}{4\omega_0} \begin{pmatrix} P & -I \\ I & P \end{pmatrix}.$$

Hence, the solution of (58b) is given by

$$(68) \quad \begin{pmatrix} w_2^j \\ w_2^i \end{pmatrix} = \frac{1}{4\omega_0} \begin{pmatrix} P & -I \\ I & P \end{pmatrix} \begin{pmatrix} \lambda - \tau P_{11} & -\lambda P_{11} - \tau \\ -\lambda - \tau P_{21} & \lambda P_{11} \\ \lambda P_{11} + \tau & \lambda - \tau P_{11} \\ -\lambda P_{11} & -\lambda - \tau P_{21} \end{pmatrix} \begin{pmatrix} \alpha_1 \phi_{4i} + \alpha_3 \phi_{4k} \\ \alpha_2 \phi_{4i} + \alpha_4 \phi_{4k} \end{pmatrix}.$$

Similarly, owing to the special form of  $f_0$  in (64), the solution of (58a) can be generated by the solutions of the following two equations:

$$(69a) \quad L(B_0)u = - \begin{pmatrix} 1 \\ -1 \end{pmatrix} \left[ \frac{B_0}{2A_0}(1 + P_{11}^2) + A_0 P_{11} P_{21} \right] \phi_{4i}^2,$$

$$(69b) \quad L(B_0)u = - \begin{pmatrix} 1 \\ -1 \end{pmatrix} \left[ \frac{B_0}{2A_0}(1 + P_{11}^2) + A_0 P_{11} P_{21} \right] \phi_{4i} \phi_{4k}.$$

Concerning the equation (58c), together with (66), one sees that its solution can

be generated from the solutions of the following four equations:

$$(70) \quad \mathcal{L} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \left[ \frac{B_0}{2A_0}(1 - P_{11}^2) - A_0 P_{11} P_{21} \right] \phi_{4i}^2,$$

$$(71) \quad \mathcal{L} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \end{pmatrix} \left[ \frac{B_0}{A_0} P_{11} + A_0 P_{21} \right] \phi_{4i}^2,$$

$$(72) \quad \mathcal{L} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \left[ \frac{B_0}{2A_0}(1 - P_{11}^2) - A_0 P_{11} P_{21} \right] \phi_{4i} \phi_{4k},$$

$$(73) \quad \mathcal{L} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \end{pmatrix} \left[ \frac{B_0}{A_0} P_{11} + A_0 P_{21} \right] \phi_{4i} \phi_{4k},$$

where

$$\mathcal{L} := \begin{pmatrix} L(B_0) & -2\omega_0 \\ 2\omega_0 & L(B_0) \end{pmatrix}.$$

As an example, we consider solution of (70). Observing its right-hand side, one sees

$$\begin{cases} \begin{pmatrix} -1 \\ 1 \end{pmatrix} \left[ \frac{B_0}{2A_0}(1 - P_{11}^2) - A_0 P_{11} P_{21} \right] \phi_{4i}^2 \\ \begin{pmatrix} -1 \\ 1 \end{pmatrix} \left[ \frac{B_0}{A_0} P_{11} + A_0 P_{21} \right] \phi_{4i}^2 \end{cases} \\ = \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} \left[ \frac{B_0}{2A_0}(1 - P_{11}^2) - A_0 P_{11} P_{21} \right] \phi_{4i}^2 + \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \left[ \frac{B_0}{A_0} P_{11} + A_0 P_{21} \right] \phi_{4i}^2. \end{cases}$$

Thus, solving the systems

$$(74) \quad \begin{pmatrix} L(B_0) & -2\omega_0 \\ 2\omega_0 & L(B_0) \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \phi_{4i}^2,$$

$$(75) \quad \begin{pmatrix} L(B_0) & -2\omega_0 \\ 2\omega_0 & L(B_0) \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \phi_{4i}^2,$$

we obtain the solution  $(u_1, u_2)^T$  of (70) as follows:

$$\begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \left[ \frac{B_0}{2A_0}(1 - P_{11}^2) - A_0 P_{11} P_{21} \right] \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} + \left( \frac{B_0}{A_0} P_{11} + A_0 P_{21} \right) \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}.$$

Moreover, we have

$$\begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} -v_2 \\ v_1 \end{pmatrix}.$$

Consequently, we need only solve (74) in order to get the solutions of (70) and (71), respectively. Correspondingly, replacing the factors  $\phi_{4i}^2$  in (74) by  $\phi_{4i} \phi_{4k}$ , and solving it, one gets solutions of (72) and (73) similarly as above. Thus, we

we have

$$(77) \quad \begin{aligned} B_3(z, \lambda, \tau) &= (I - Q)j_3 R \left( \sum_{i=1}^4 \alpha_i \psi_i + w_2, \lambda, \tau \right) \\ &= B_2(z, \lambda, \tau) + (I - Q)(2R_1(z, w_2(\eta)) + \lambda R_2(w_2(\eta))) \\ &\quad + R_3(z, z, z) + \lambda R_4(z, z) - \tau \partial_z w_2(\eta). \end{aligned}$$

Again,  $B_3$  is  $D_4 \times S^1$  equivariant. Once  $w_2(\eta)$  is known,  $B_3(\eta)$  follows from simple calculations consisting mainly of  $L^2$ -products in  $C_{2\pi}^2$ .

#### REFERENCES

1. P. Ashwin and Z. Mei: *Liepsano-Schmidt reduction at Hopf bifurcation of the Brusselator equations on a square*. Preprint, University of Warwick, 1992.
2. Z. Mei: *Path following around Corank-2 bifurcation points of a semi-linear elliptic problem with symmetry*. *Computing* 47:69-85, 1991.
- P. ASHWIN, MATHEMATICS INSTITUTE, UNIVERSITY OF WARWICK, COVENTRY CV4 7AL, UK
- K. BÖHMER, FB MATH., UNIVERSITÄT MARBURG, LAHNBERGE, D-35032 MARBURG, FRG
- Z. MEI, FB MATH., UNIVERSITÄT MARBURG, LAHNBERGE, D-35032 MARBURG, FRG AND DEPT. MATH., XIAN JIAOTONG UNIVERSITY, XI'AN 710049, PRC

can calculate all the coefficients  $w_2^{kij}$  for  $k = 0, \dots, 4$  and  $i, j = 1, \dots, 4$  from the solutions of the problems (69), (69b) and (74).

These problems are discretized using finite differences and then solved directly using the bandedness of the matrices in the discrete problems to give the coefficients in the various quadratic terms. Thus we can find the solutions  $w_2^k$  of (58a), (58c) in the form

$$(76) \quad w_2^k = \sum_{i,j=1}^4 \alpha_i \alpha_j w_2^{kij}, \quad k = 0, 3, 4.$$

The equivariance of the equations in (58) leads to the relations

$$\gamma w_2^i(\alpha) = w_2^j(\gamma\alpha) \quad \forall \gamma \in D_4 \times S^1, \quad i = 0, 3, 4.$$

Thus, once the coefficients  $w_2^{i11}, w_2^{i12}, w_2^{i13}, w_2^{i14}$  of the terms  $\alpha_i^2, \alpha_i \alpha_j, \alpha_j^2, \alpha_i \alpha_j \alpha_k, \alpha_i \alpha_k$  in the expansion of  $w_2^i, i = 0, 3, 4$ , are known, all other terms can be derived via group actions. Hence to solve the equations (58), we solve four equations corresponding to  $(i, j) = (1, 1), (1, 2), (1, 3), (1, 4)$  in the expansion of the right-hand side of (58) with respect to  $\alpha_1, \dots, \alpha_4$ . Even in the computation of these coefficients, the special structure of the systems allows further decomposition of the solutions and reduction of computational effort. In fact, the right-hand sides of (58) consist of products of various eigenfunctions of the Laplacian on the square and possess rich nodal line properties; in view of the underlying periodic boundary conditions of these linear systems, we can often restrict the problem to smaller fundamental domains; see, e.g., Mei [2].

**4.2. Calculating  $B_3$ .** Once again, we can use the symmetries of the problem to considerably reduce the number of calculations required for the bifurcation equations truncated to third order.

Note that we know all the second-order terms from the calculation of  $B_2$ , and so we only need to consider the third-order terms from the right-hand side of the equivalent to equation (11). This was performed by a Maple code, which generated the pointwise values of the function (in terms of the  $w_{2i}$ ) that, when integrated, gave the coefficients of  $B_3$ . The Maple expression was then transcribed into (10k byte of) optimized Fortran formula. For simplicity, we briefly give the main idea used to calculate  $B_3$ . For  $u = (u_1, u_2)^T, v = (v_1, v_2)^T \in C_{2\pi}^2$ , we define

$$\begin{aligned} R_1(u, v) &:= \begin{pmatrix} 1 \\ -1 \end{pmatrix} \left[ \frac{B_0}{A_0} u_1 v_1 + 2A_0 \frac{u_1 v_2 + u_2 v_1}{2} \right], \quad R_2(u) := \begin{pmatrix} 1 \\ -1 \end{pmatrix} u_1, \\ R_3(u, v, w) &:= \begin{pmatrix} 1 \\ -1 \end{pmatrix} u_1^2 w_2, \quad R_4(u, v) := \begin{pmatrix} 1 \\ -1 \end{pmatrix} u_1 v_1 / A_0. \end{aligned}$$

Hence, for

$$\eta := (z, \lambda, \tau) = \left( \sum_{i=1}^4 \alpha_i \psi_i, \lambda, \tau \right) \in \text{Ker}(\partial_u \Phi_0) \times \mathbb{R}^2,$$